

## Scaling of the geomagnetic secular variation time scales

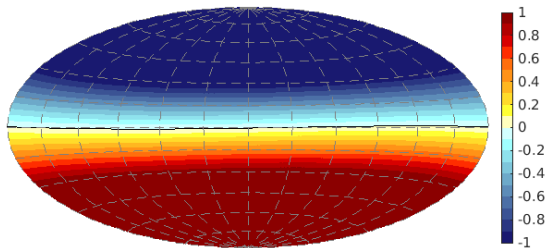
Yue-Kin Tsang

*School of Mathematics, Statistics and Physics*  
*Newcastle University*

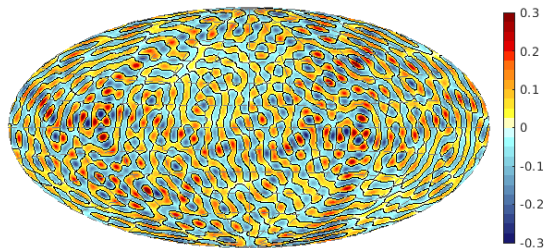
Chris Jones  
*University of Leeds*

# Time variation of the geomagnetic field at different spatial scales

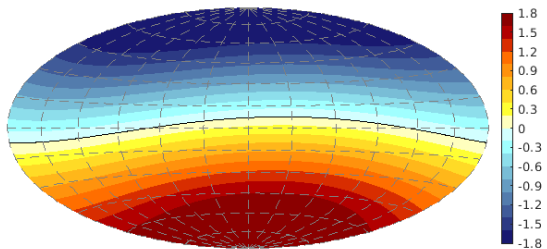
$B_r$  for  $l = 1$  at  $r = 1.00 r_{\text{cmb}}$  and  $t = 2.01799$



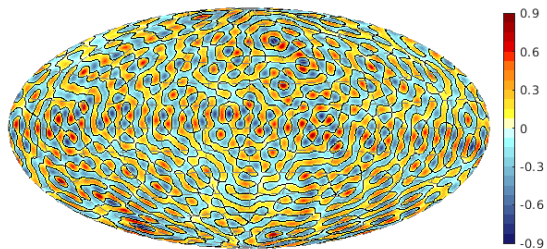
$B_r$  for  $l = 40$  at  $r = 1.00 r_{\text{cmb}}$  and  $t = 2.01799$



$B_r$  for  $l = 1$  at  $r = 0.50 r_{\text{cmb}}$  and  $t = 2.01799$



$B_r$  for  $l = 40$  at  $r = 0.50 r_{\text{cmb}}$  and  $t = 2.01799$



# Spectra: to study properties at different spatial scales

## (1) Lowes spectrum ( $r \geq r_{\text{cmb}}$ )

$$R(l, r, t) = \left(\frac{a}{r}\right)^{2l+4} (l+1) \sum_{m=0}^l [g_{lm}^2(t) + h_{lm}^2(t)],$$

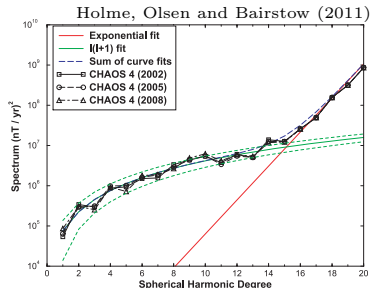
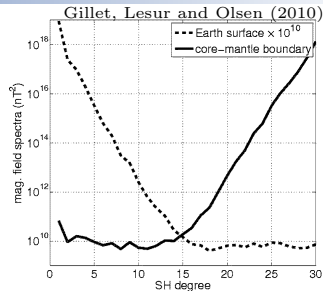
$$\sum_{l=1}^{\infty} R(l, r, t) = \frac{1}{4\pi} \oint |\mathbf{B}(r, \theta, \phi, t)|^2 \sin \theta \, d\theta \, d\phi$$

( $a$  = Earth's radius)

## (2) Secular variation spectrum ( $r \geq r_{\text{cmb}}$ )

$$R_{\text{sv}}(l, r, t) = \left(\frac{a}{r}\right)^{2l+4} (l+1) \sum_{m=0}^l [\dot{g}_{lm}^2(t) + \dot{h}_{lm}^2(t)]$$

$$\sum_{l=1}^{\infty} R_{\text{sv}}(l, r, t) = \frac{1}{4\pi} \oint |\dot{\mathbf{B}}(r, \theta, \phi, t)|^2 \sin \theta \, d\theta \, d\phi, \quad \dot{\mathbf{B}} = \frac{\partial \mathbf{B}}{\partial t}$$



## Secular variation time-scale spectrum

$R(l) \sim$  “amount” of  $B^2$  in spatial scale  $l$

$R_{\text{sv}}(l) \sim$  “amount” of  $\dot{B}^2$  in spatial scale  $l$

$$\tau_{\text{sv}}(l, t) = \sqrt{\frac{R}{R_{\text{sv}}}} = \sqrt{\frac{\sum_{m=0}^l (g_{lm}^2 + h_{lm}^2)}{\sum_{m=0}^l (\dot{g}_{lm}^2 + \dot{h}_{lm}^2)}} \quad (r \geq r_{\text{cmb}})$$

- characteristic time scale of magnetic field structures with spatial scale characterised by  $l$
- numerical simulations and *some* satellite data support the simple power-law:  $\tau_{\text{sv}}(l) \sim l^{-1}$  (but there are debates about this)
- theoretically, there is an argument based on the frozen-flux hypothesis that involves the radial magnetic field and the horizontal derivative:

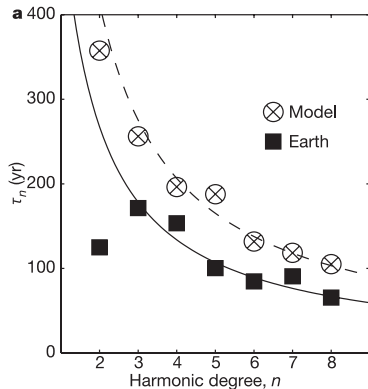
$$\begin{aligned}\dot{B}_r &= -\nabla_{\text{h}} \cdot (\mathbf{u}_{\text{h}} B_r) \\ \nabla_{\text{h}} &\sim \sqrt{l(l+1)} \sim l \quad \text{and} \quad \mathbf{u}_{\text{h}} \sim U \\ \tau_{\text{sv}} &\sim B_r / \dot{B}_r \sim l^{-1}\end{aligned}$$

# Scaling of $\tau_{\text{SV}}(l)$ : observations and numerical models

Christensen and Tilgner (2004)

observation data 1840–1990

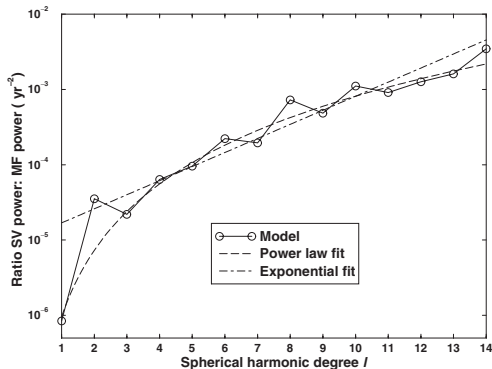
and numerical dynamo models



$$\tau_{\text{SV}} \sim l^{-1}$$

Holme and Olsen (2006)

satellite data 1999–2003

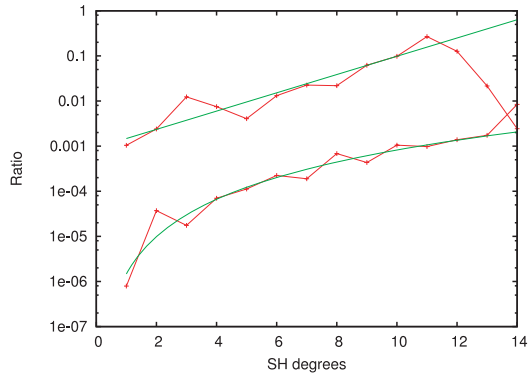


$$\frac{R_{\text{SV}}}{R} \sim l^{2.9}$$
$$\Rightarrow \tau_{\text{SV}} \sim l^{-1.45}$$

# Scaling of $\tau_{\text{sv}}(l)$ : observations and numerical models

Lesur et al. (2008)

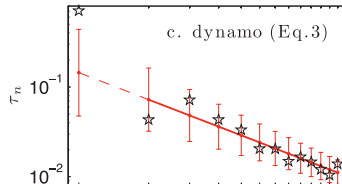
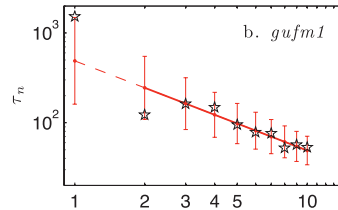
6yr CHAMP + 5yr observatory data



$$\frac{R_{\text{sv}}}{R} \sim l^{2.75}$$
$$\Rightarrow \tau_{\text{sv}} \sim l^{-1.38}$$

Lhuillier et al. (2011)

“historical data” 1840–1990, satellite data (2005) and numerical dynamo models



$$\tau_{\text{sv}} \sim l^{-1}$$

## The scaling exponent $\gamma$

$$\tau_{\text{sv}}(l) \sim l^{-\gamma} \quad (\text{excluding } l = 1)$$

### Questions:

1.  $\tau_{\text{sv}}$  is defined using the Gauss coefficients obtained from  $\mathbf{B}$  outside the outer core.  
Do  $\tau_{\text{sv}}$  and the scaling law  $\tau_{\text{sv}} \sim l^{-1}$  describe the time variation of  $\mathbf{B}$  inside the outer core?  
*[No. Inside the outer core,  $\mathbf{B}$  is not potential.  $\dot{B}_r$ ,  $\dot{B}_\theta$  and  $\dot{B}_\phi$  may all be important.]*
2. Does the frozen-flux argument explain the scaling  $\gamma = 1$  observed at the surface?  
*[No. Magnetic diffusion is important near the CMB.]*
3. What are the mechanisms controlling the scaling  $\tau_{\text{sv}} \sim l^{-\gamma}$ ?  
*[It varies, depending on locations and the boundary conditions.]*

## Generalisation to inside the dynamo region (outer core)

Recall the definition of the Lowes spectrum  $R(l, r, t)$  for  $r \geq r_{\text{cmb}}$ ,

$$\mathbf{B} = -\nabla \Psi, \quad \Psi(r, \theta, \phi, t) = a \sum_{l=1}^{\infty} \sum_{m=0}^l \left(\frac{a}{r}\right)^{l+1} \hat{P}_{lm}(\cos \theta) [g_{lm}(t) \cos m\phi + h_{lm}(t) \sin m\phi]$$

$$\frac{1}{4\pi} \oint |\mathbf{B}(r, \theta, \phi, t)|^2 \sin \theta \, d\theta \, d\phi = \sum_{l=1}^{\infty} R(l, r, t)$$

$$R(l, r, t) = \left(\frac{a}{r}\right)^{2l+4} (l+1) \sum_{m=0}^l [g_{lm}^2(t) + h_{lm}^2(t)]$$

For any  $r$ , expand in vector spherical harmonics,

$$\mathbf{B}(r, \theta, \phi, t) = \sum_{lm} [\mathbf{q}_{lm}(r, t) \hat{\mathbf{Y}}_{lm}(\theta, \phi) + \mathbf{s}_{lm}(r, t) \hat{\boldsymbol{\Psi}}_{lm}(\theta, \phi) + \mathbf{t}_{lm}(r, t) \hat{\boldsymbol{\Phi}}_{lm}(\theta, \phi)]$$

We define the magnetic energy spectrum  $F(l, r, t)$  for all  $r$ :

$$\sum_{l=1}^{\infty} F(l, r, t) \equiv \frac{1}{4\pi} \oint |\mathbf{B}(r, \theta, \phi, t)|^2 \, d\Omega = \sum_{l=1}^{\infty} \left[ \frac{1}{(2l+1)} \sum_{m=0}^l (|q_{lm}|^2 + |s_{lm}|^2 + |t_{lm}|^2) (4 - 3\delta_{m,0}) \right]$$



## Generalisation to inside the dynamo region (outer core)

$$F(l, r, t) = \frac{1}{(2l+1)} \sum_{m=0}^l (|q_{lm}|^2 + |s_{lm}|^2 + |t_{lm}|^2)(4 - 3\delta_{m,0})$$

Similarly, define the **time variation spectrum**  $F_{\dot{B}}(l, r, t)$ :

$$\dot{\mathbf{B}}(r, \theta, \phi, t) = \sum_{lm} [\dot{q}_{lm}(r, t) \hat{\mathbf{Y}}_{lm}(\theta, \phi) + \dot{s}_{lm}(r, t) \hat{\mathbf{\Psi}}_{lm}(\theta, \phi) + \dot{t}_{lm}(r, t) \hat{\mathbf{\Phi}}_{lm}(\theta, \phi)]$$

$$\sum_{l=1}^{\infty} F_{\dot{B}}(l, r, t) \equiv \frac{1}{4\pi} \oint |\dot{\mathbf{B}}(r, \theta, \phi, t)|^2 d\Omega = \sum_{l=1}^{\infty} \left[ \frac{1}{(2l+1)} \sum_{m=0}^l (|\dot{q}_{lm}|^2 + |\dot{s}_{lm}|^2 + |\dot{t}_{lm}|^2)(4 - 3\delta_{m,0}) \right]$$

Then, the **magnetic time-scale spectrum** is defined as:

$$\tau(l, r) = \left\langle \sqrt{\frac{F(l, r, t)}{F_{\dot{B}}(l, r, t)}} \right\rangle_t$$

Outside the dynamo region:  $F = R$  ,  $F_{\dot{B}} = R_{sv}$  ,  $\tau = \tau_{sv}$

## A numerical model of geodynamo

Boussinesq, compositional driven, rotating convection of a electrically conducting fluid:

$$\frac{D\mathbf{u}}{Dt} + 2\frac{Pm}{Ek}\hat{\mathbf{z}} \times \mathbf{u} = -\frac{Pm}{Ek}\nabla\Pi' + \left(\frac{RaPm^2}{Pr}\right)C'\mathbf{r} + \frac{Pm}{Ek}(\nabla \times \mathbf{B}) \times \mathbf{B} + Pm\nabla^2\mathbf{u},$$

$$\frac{\partial\mathbf{B}}{\partial t} = \nabla \times (\mathbf{u} \times \mathbf{B}) + \nabla^2\mathbf{B}$$

$$\frac{DC}{Dt} = \frac{Pm}{Pr}\nabla^2C - 1$$

$$\nabla \cdot \mathbf{u} = 0$$

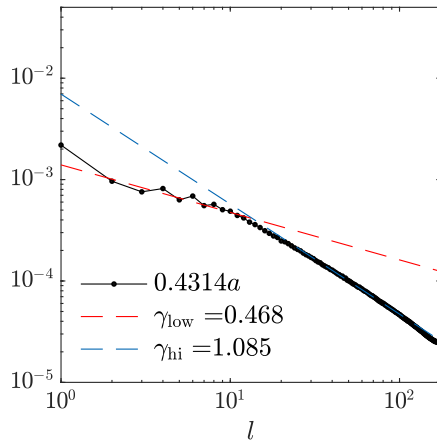
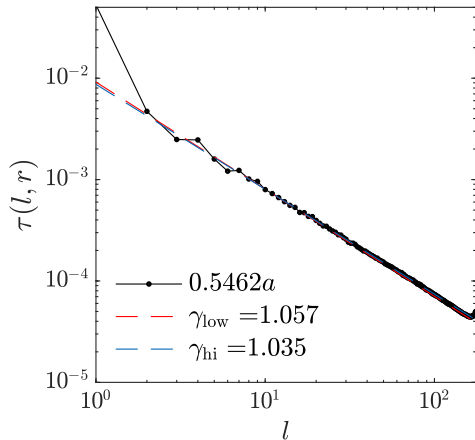
$$\nabla \cdot \mathbf{B} = 0$$

Boundary conditions: **no-slip** for  $\mathbf{u}$ , Neumann for  $C$

Domain: a spherical shell  $0.1912a \leq r \leq 0.5462a$

$$Ra = 2.7 \times 10^8, Ek = 2.5 \times 10^{-5}, Pm = 2.5, Pr = 1$$

## Magnetic time-scale spectrum $\tau(l, r)$ at different depth

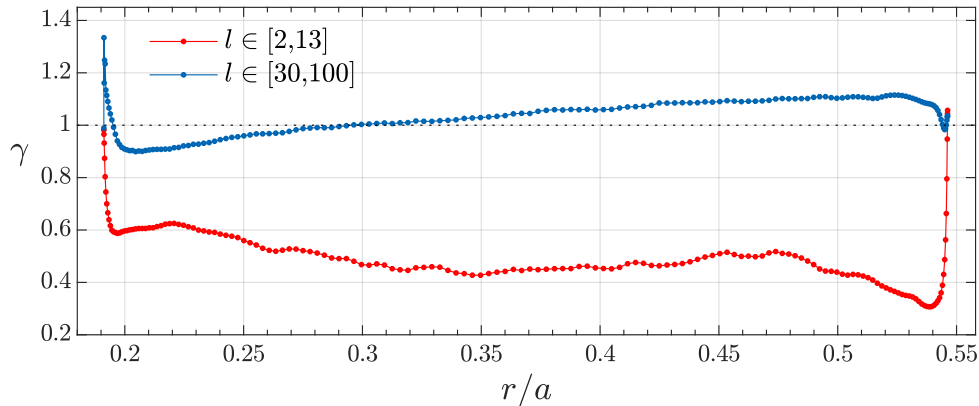


For the **large-scale** modes (small  $l$ ),

● at the surface:  $\tau \sim l^{-1}$

● in the interior:  $\tau \sim l^{-0.5}$ , the large-scale modes speeds up in the interior!

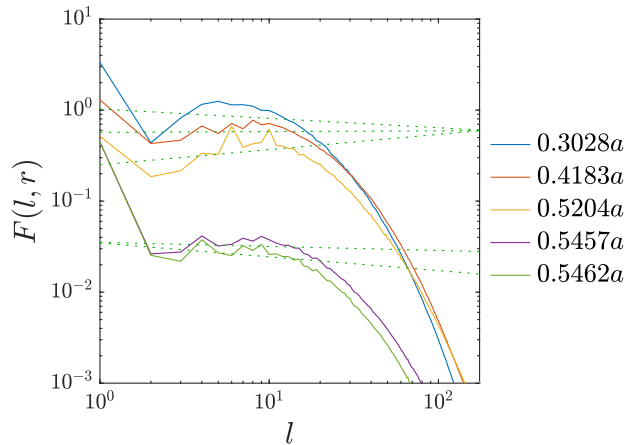
## Change in the scaling of $\tau$ : where does it occur?



●  $\gamma$  for the large-scale modes increases sharply within a boundary layer under CMB

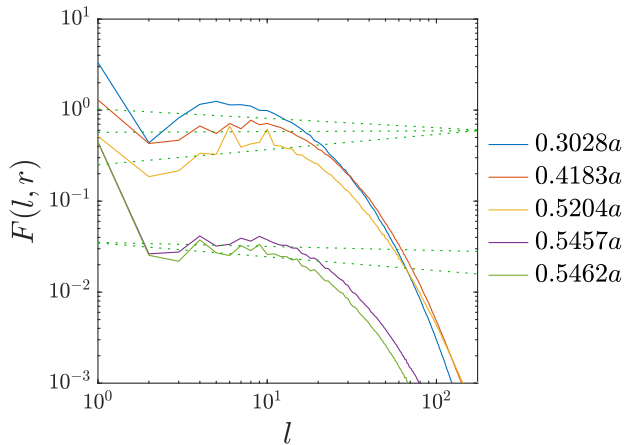
Focus on the large scales in following discussion ...

## Change in the scaling of $\tau$ : who causes it?



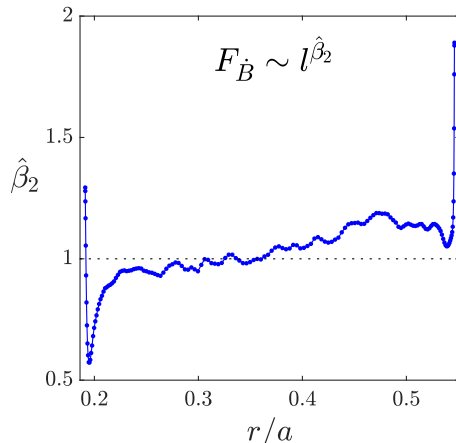
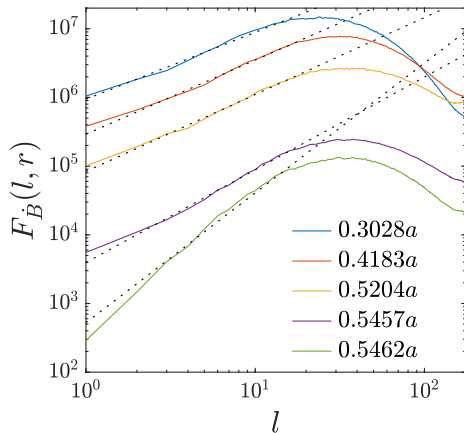
$$\tau \sim \sqrt{\frac{F}{F_{\dot{B}}}}$$

## Change in the scaling of $\tau$ : who causes it?



$$\tau \sim \sqrt{\frac{F}{F_{\dot{B}}}} \sim \sqrt{\frac{l^0}{F_{\dot{B}}}} \sim F_{\dot{B}}^{-\frac{1}{2}}$$

## Change in the scaling of $\tau$ : who causes it?

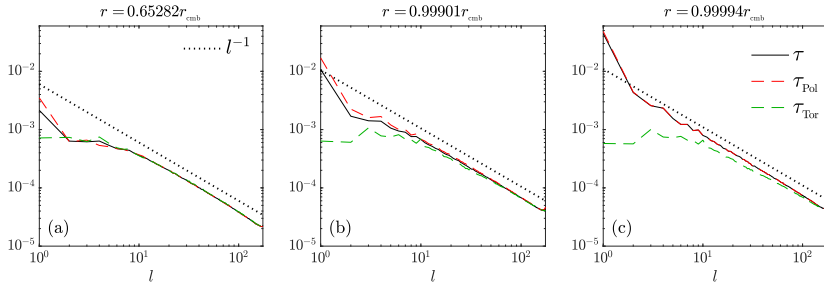


$$\tau \sim \sqrt{\frac{F}{F_{\dot{B}}}} \sim \sqrt{\frac{l^0}{F_{\dot{B}}}} \sim F_{\dot{B}}^{-\frac{1}{2}}$$

$$F_{\dot{B}} \sim l \implies \tau \sim l^{-0.5} \quad (\text{interior})$$

$$F_{\dot{B}} \sim l^2 \implies \tau \sim l^{-1} \quad (\text{surface})$$

# Transition in terms of poloidal and toroidal time scales

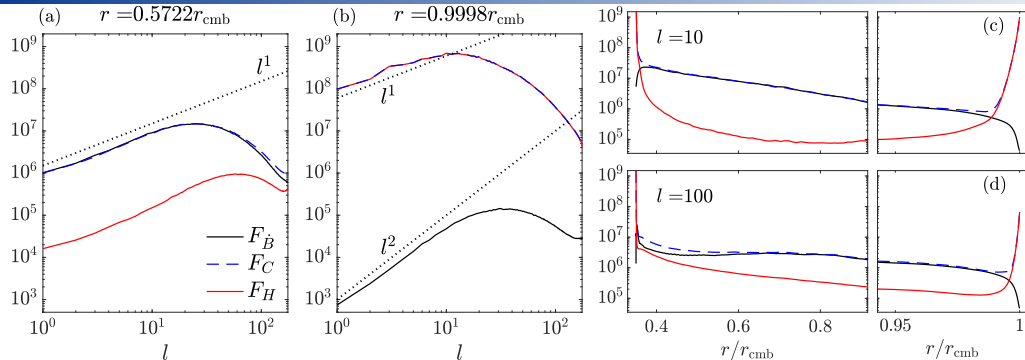


$$\mathbf{B} = \mathbf{B}_{\text{Pol}} + \mathbf{B}_{\text{Tor}} , \quad \tau_{\text{Pol}} = \sqrt{\frac{\text{spectrum of } \mathbf{B}_{\text{Pol}}}{\text{spectrum of } \dot{\mathbf{B}}_{\text{Pol}}}} , \quad \tau_{\text{Tor}} = \sqrt{\frac{\text{spectrum of } \mathbf{B}_{\text{Tor}}}{\text{spectrum of } \dot{\mathbf{B}}_{\text{Tor}}}}$$

- interior:  $\mathbf{B}_{\text{Pol}}$  and  $\mathbf{B}_{\text{Tor}}$  are equally important,  $\tau \approx \tau_{\text{Pol}} \approx \tau_{\text{Tor}} \sim l^{-0.5}$
- no change in shape for  $\tau_{\text{Tor}}$ , but the magnetic boundary condition requires  $\mathbf{B}_{\text{Tor}} \rightarrow 0$  as  $r \rightarrow r_{\text{cmb}}$ , so  $\tau_{\text{Tor}}$  becomes irrelevant near the CMB
- As  $r \rightarrow r_{\text{cmb}}$ :  $\tau_{\text{Pol}} \sim l^{-0.5}$  transitions to  $\tau_{\text{Pol}} \sim l^{-1}$  and  $\mathbf{B} \approx \mathbf{B}_{\text{Pol}} \Rightarrow \tau \approx \tau_{\text{Pol}} \sim l^{-1}$
- contribution of  $\dot{\mathbf{B}}_{\text{Tor}}$  ( $\dot{B}_\theta$  and  $\dot{B}_\phi$ ) to  $\dot{\mathbf{B}}$  in the interior masked by the boundary conditions



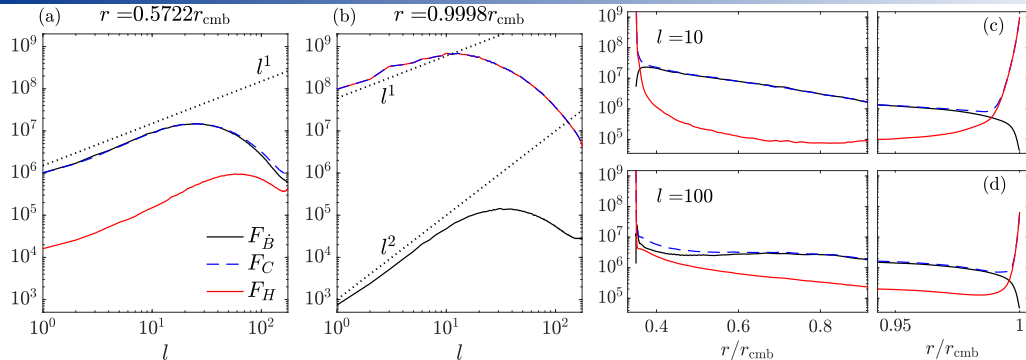
# What processes control the scaling of $\tau$ in the interior?



$$\dot{\mathbf{B}} = \nabla \times (\mathbf{u} \times \mathbf{B}) + \eta \nabla^2 \mathbf{B} = \mathbf{C} + \mathbf{H}$$

- $F_{\dot{B}} \approx F_C$  (magnetic diffusion negligible),  $F_{\dot{B}} \sim F_C \sim l \implies \tau \sim l^{-0.5}$
- frozen-flux argument not applicable:
  - $\dot{B}_\theta$  and  $\dot{B}_\phi$  contribute significantly to  $\dot{\mathbf{B}}$
  - $\dot{B}_\theta$  and  $\dot{B}_\phi$  dominated by radial derivatives in the induction term  $\mathbf{C}$

# What processes control the scaling of $\tau$ near the CMB?



$$\dot{\mathbf{B}} = \nabla \times (\mathbf{u} \times \mathbf{B}) + \eta \nabla^2 \mathbf{B} = \mathbf{C} + \mathbf{H}$$

- $F_{\dot{B}} \sim l^2 \implies \tau \sim l^{-1}$ , but ...
- $F_C \approx F_H$ ,  $F_C \sim F_H \sim l$  ( $\mathbf{C}$  and  $\mathbf{H}$  cancel to leading order)
- $\mathbf{H}$  is important  $\implies$  frozen-flux argument is not applicable in explaining  $\tau \sim l^{-1}$  at the CMB

## Summary

- scaling of  $\tau(l, r)$  with  $l$  observed outside the outer core is different from that in the interior
- for the large scales:

$$\begin{aligned}\tau &\sim l^{-0.5}, & \text{in the interior} \\ \tau &\sim l^{-1}, & \text{at the CMB}\end{aligned}$$

the transition occurs within a boundary layer under the CMB

- time variation of  $\mathbf{B}_{\text{Tor}}$  in the interior is hidden from surface observation by the magnetic boundary condition at the CMB
- for the large scales,  $F_{\dot{B}}$  is responsible for the transition ( $\tau = \sqrt{F/F_{\dot{B}}}$ )
  - in the interior, induction term  $\mathbf{C}$  dominates,  $\dot{\mathbf{B}} \approx \mathbf{C}$  and  $F_{\dot{B}} \sim l$
  - at the CMB (no-slip), balance between the induction term and magnetic diffusion leads to  $F_{\dot{B}} \sim l^2$ , meaning frozen-flux argument not applicable