

An energy-entropy method for global stability in two-dimensional hydrodynamics

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Kolmogorov Flows

$$\zeta_t + u\zeta_x + v\zeta_y + \beta\psi_x = -\mu\zeta + \cos x + \nu\nabla^2\zeta$$

velocity: $(u, v) = (-\psi_y, \psi_x)$ (2-D periodic domain)

vorticity: $\zeta(x, y) = v_x - u_y = \nabla^2\psi$

● *single-scaled* sinusoidal body force (at $k_f = 1$)

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- 2D flows: dual conservation of energy E and enstrophy Z

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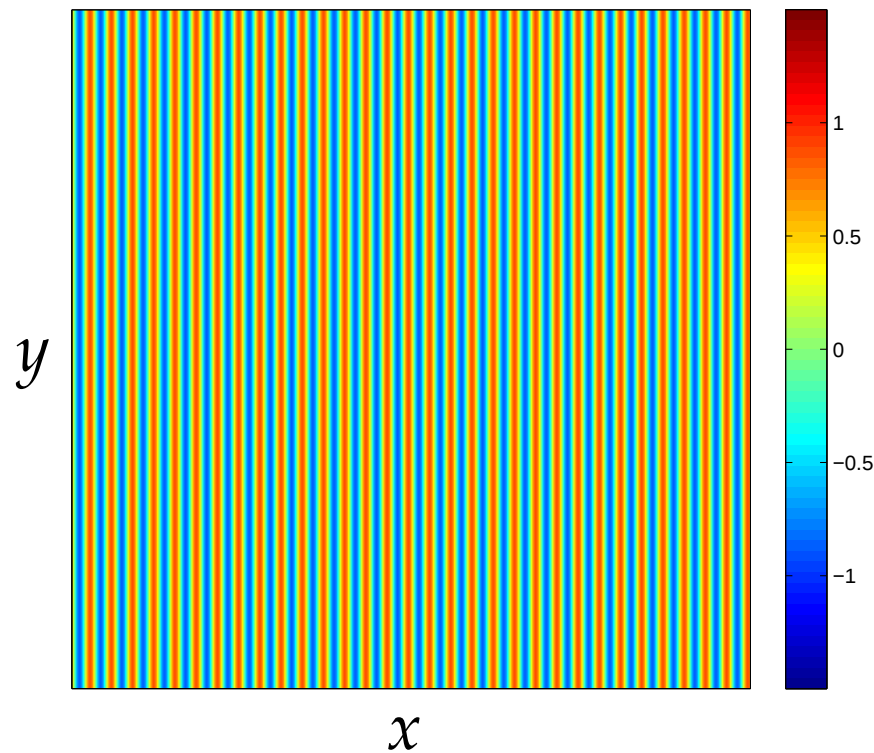
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We shall first consider the inviscid case: $\nu = 0$

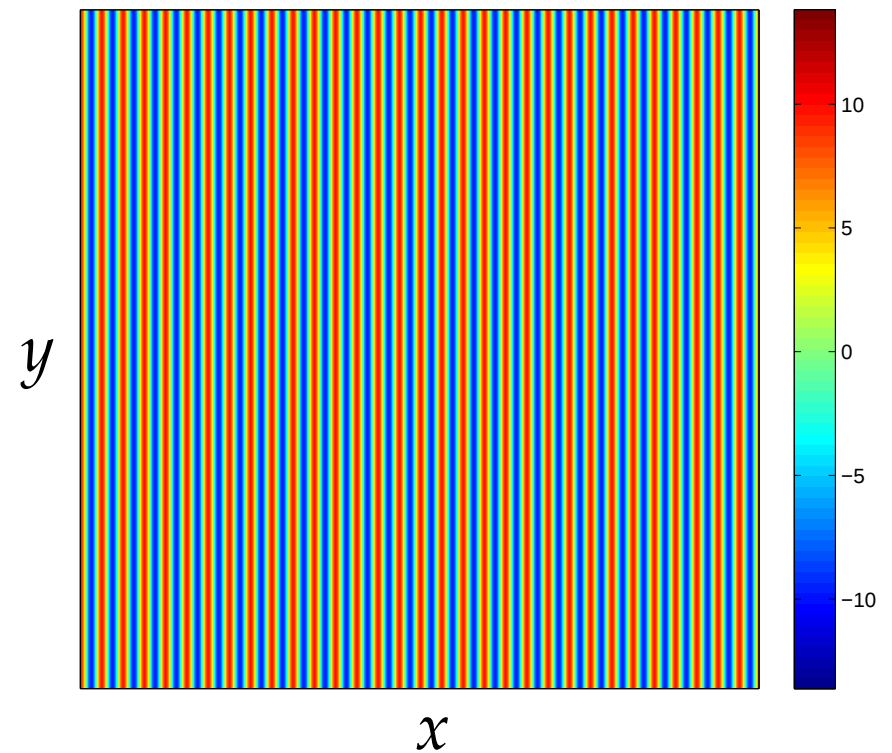
An Inviscid Laminar Solution

$$\zeta_L(x) = a \cos(x - x_\beta)$$

$$a = \frac{1}{\sqrt{\beta^2 + \mu^2}} \quad , \quad x_\beta = \tan^{-1} \frac{\beta}{\mu}$$



$$\mu = 0.5 \quad \beta = 1.0$$

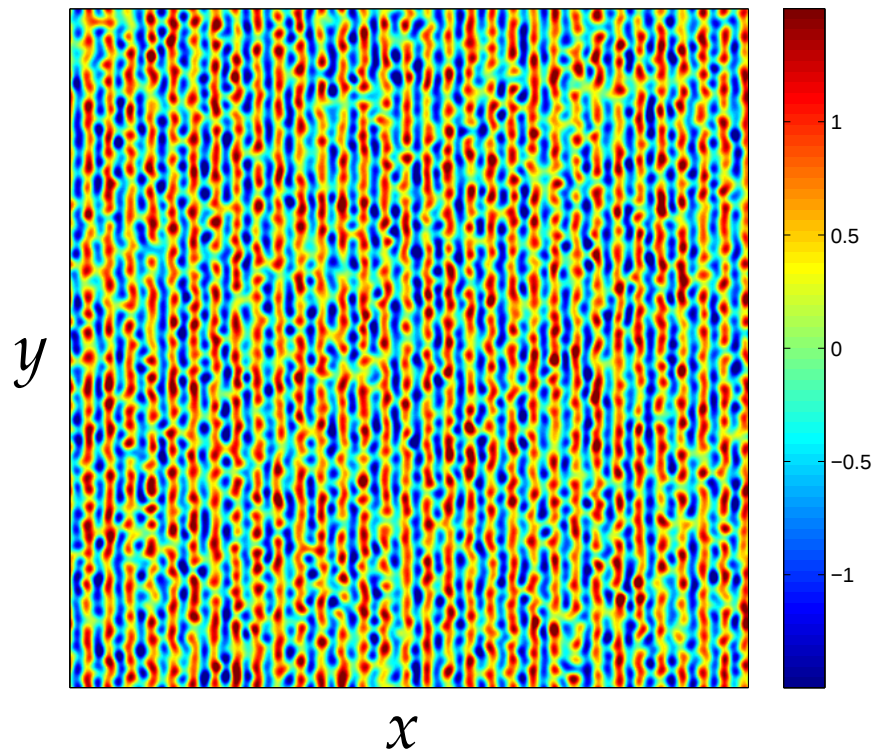


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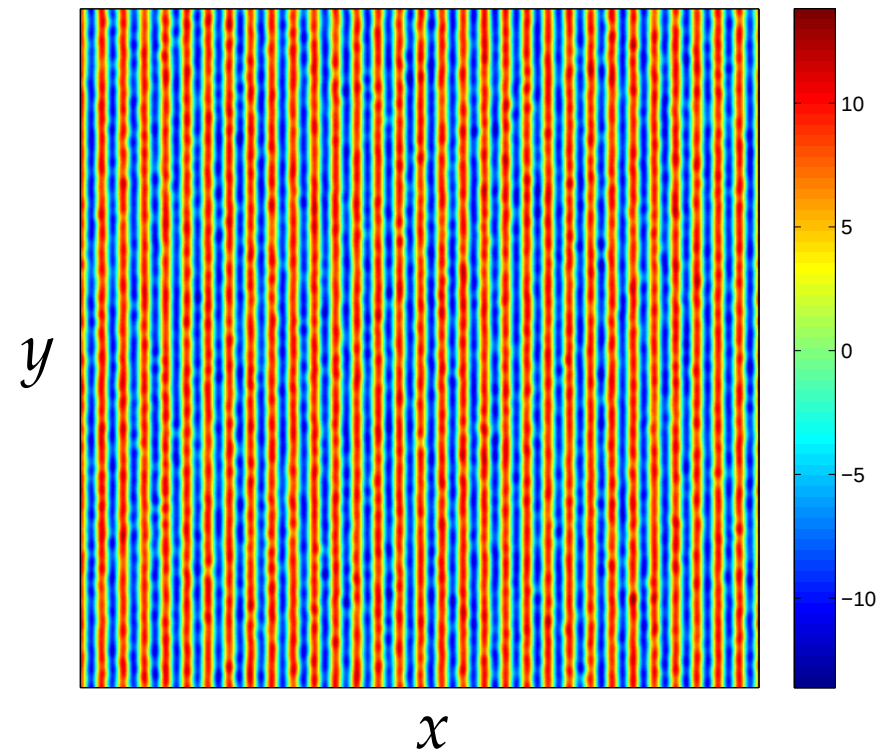
Stability of the Laminar Solution

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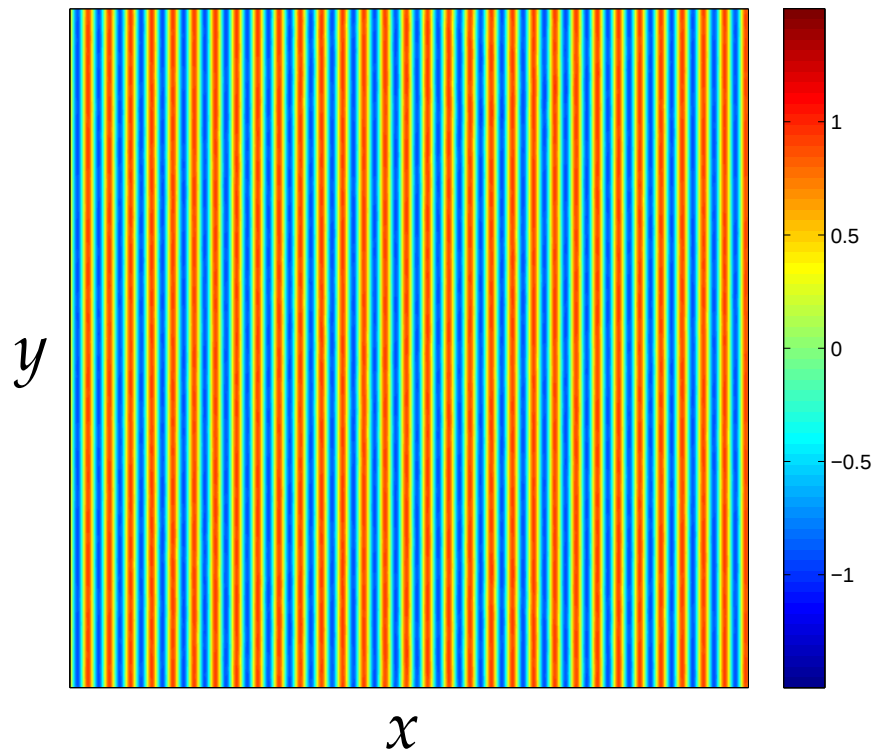


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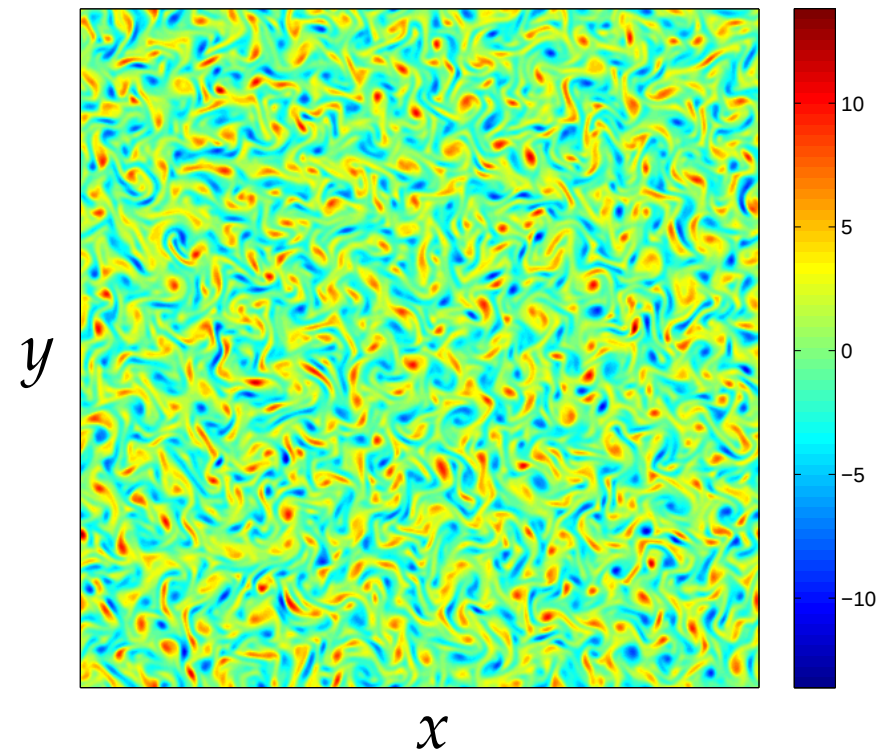
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stable

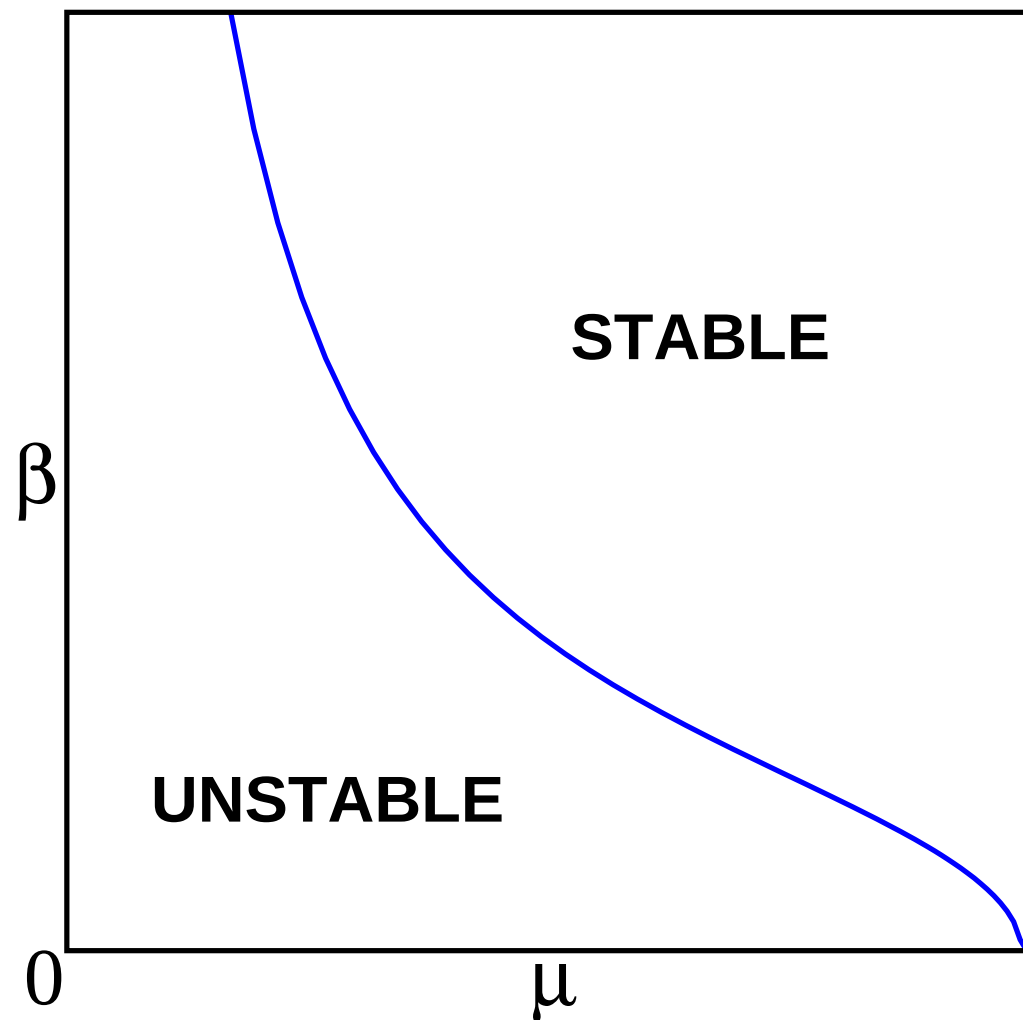


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unstable

Goal: Neutral Curve

$$\zeta_t + u\zeta_x + v\zeta_y + \beta\psi_x = -\mu\zeta + \cos x$$



Stability Analysis

$$\psi(x, y, t) = \psi_L(x) + \varphi(x, y, t)$$

- Linear Instability
 - assume infinitesimal disturbance $\varphi \sim e^{-i\omega t}$
 - $\Im\{\omega\} > 0 \Rightarrow \psi_L$ is unstable
 - gives sufficient condition for **instability**
- Global Stability (Asymptotic Stability)
 - φ is **not** assumed to be small
 - **disturbance energy**

$$E_\varphi(t) = \frac{1}{2} \langle |\nabla \varphi|^2 \rangle \rightarrow 0 \quad \text{as } t \rightarrow \infty$$

- gives sufficient condition for **stability**

Energy Method

$$\nabla^2 \psi_t + J(\psi, \nabla^2 \psi) + \beta \psi_x = -\mu \nabla^2 \psi + \cos x$$

$$\psi_L(x) = -a \cos(x - x_\beta)$$

Time evolution equation for φ ($\psi = \psi_L + \varphi$):

$$\nabla^2 \varphi_t + J(\psi_L, \nabla^2 \varphi) + J(\varphi, \nabla^2 \psi_L) + J(\varphi, \nabla^2 \varphi) + \beta \varphi_x = -\mu \nabla^2 \varphi$$

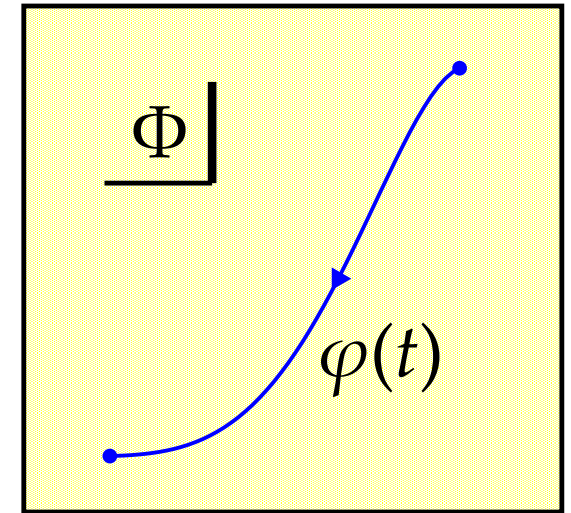
$$\begin{aligned} \therefore \quad \frac{dE_\varphi}{dt} &= \left\langle \varphi J(\psi_L, \nabla^2 \varphi) \right\rangle - \mu \left\langle |\nabla \varphi|^2 \right\rangle \\ &= a \left\langle \varphi_x \varphi_y \cos x \right\rangle - 2\mu E_\varphi \end{aligned}$$

Energy Method

$$\frac{dE_\varphi}{dt} = 2 \left(a\mathcal{R}[\varphi] - \mu \right) E_\varphi$$

where

$$\mathcal{R}[\varphi] \equiv \frac{\langle \varphi_x \varphi_y \cos x \rangle}{\langle |\nabla \varphi|^2 \rangle}$$



Now define $\mathcal{R}_* \equiv \max_{\varphi \in \Phi} \mathcal{R}[\varphi]$

Φ : set of all functions satisfying periodic boundary conditions

Then,

$$\frac{dE_\varphi}{dt} < 2(a\mathcal{R}_* - \mu) E_\varphi$$

$$\Rightarrow E_\varphi(t) < E_\varphi(0) e^{2(a\mathcal{R}_* - \mu)t} \quad (\text{Gronwall's inequality})$$

Energy Method

$$E_{\varphi}(t) < E_{\varphi}(0) e^{2(a\mathcal{R}_* - \mu)t}$$

$$\therefore E_{\varphi}(t \rightarrow \infty) \rightarrow 0 \quad \text{if } a\mathcal{R}_* - \mu < 0$$

Neutral condition

$$a = \frac{1}{\mathcal{R}_*} \mu \quad \Rightarrow \quad \boxed{\beta = \sqrt{\frac{\mathcal{R}_*^2}{\mu^2} - \mu^2}}$$

Optimal solution

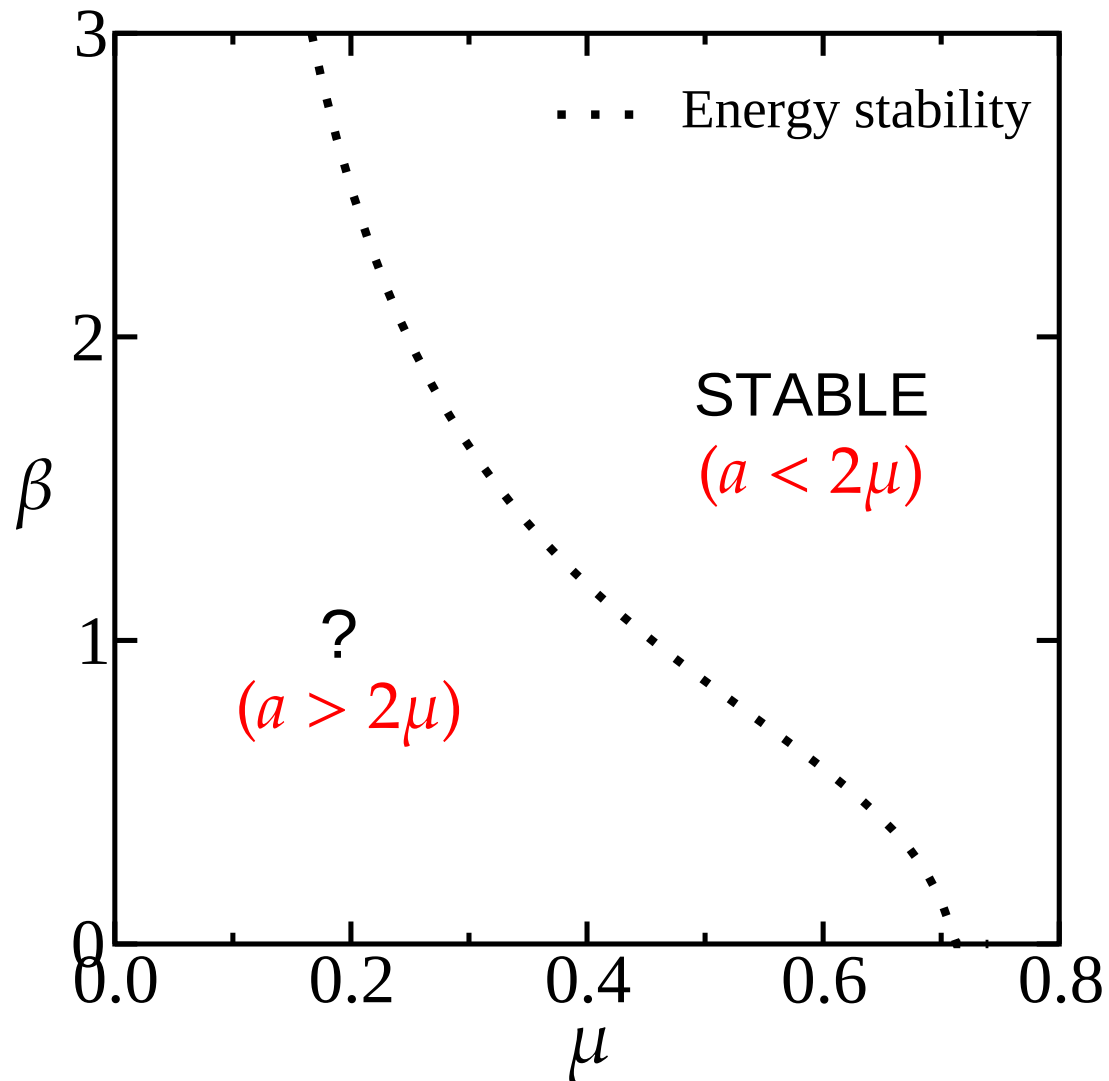
$$\text{Maximize: } \mathcal{R}[\varphi] \equiv \frac{\langle \varphi_x \varphi_y \cos x \rangle}{\langle |\nabla \varphi|^2 \rangle} \quad \text{over the set } \Phi.$$

$$\mathcal{R}_* = \mathcal{R}[\varphi_*] = \frac{1}{2}$$

$$\varphi_*(x, y) = \Re \left\{ e^{i^l y} \tilde{\varphi}(x) \right\} \quad \text{with } l \rightarrow \infty$$

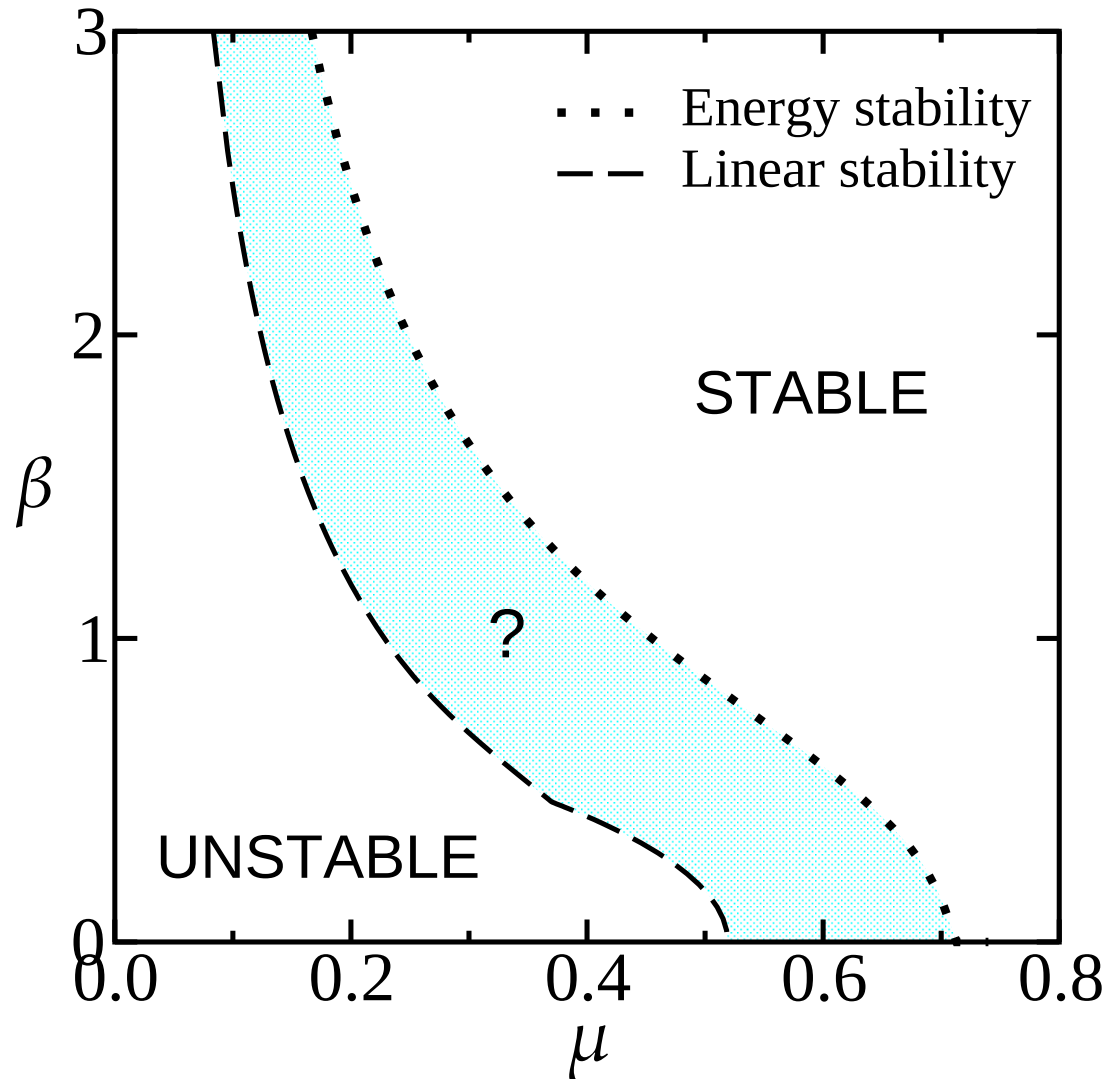
Energy Stability Curve

$$\beta = \sqrt{\frac{1}{4\mu^2} - \mu^2} \quad (a = 2\mu)$$



Energy Stability and Linear Stability Curve

$$\beta = \sqrt{\frac{1}{4\mu^2} - \mu^2} \quad (a = 2\mu)$$



Energy-Enstrophy Balance

Limitations of the energy method: requires $E_\varphi(t)$ to decrease **monotonically** for all φ , thus excludes transient growth of $E_\varphi(t)$

Disturbance enstrophy: $Z_\varphi = \frac{1}{2} \langle (\nabla^2 \varphi)^2 \rangle$

$$\frac{dZ_\varphi}{dt} = a \langle \varphi_x \varphi_y \cos x \rangle - 2\mu Z_\varphi$$

Recall,

$$\frac{dE_\varphi}{dt} = a \langle \varphi_x \varphi_y \cos x \rangle - 2\mu E_\varphi$$

Then,

$$\frac{d}{dt}(E_\varphi - Z_\varphi) = -2\mu(E_\varphi - Z_\varphi)$$

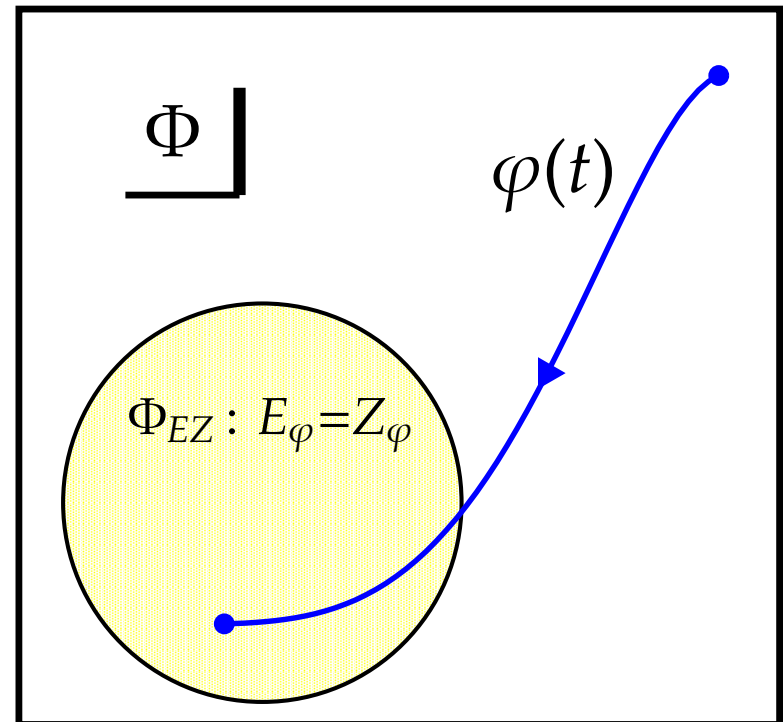
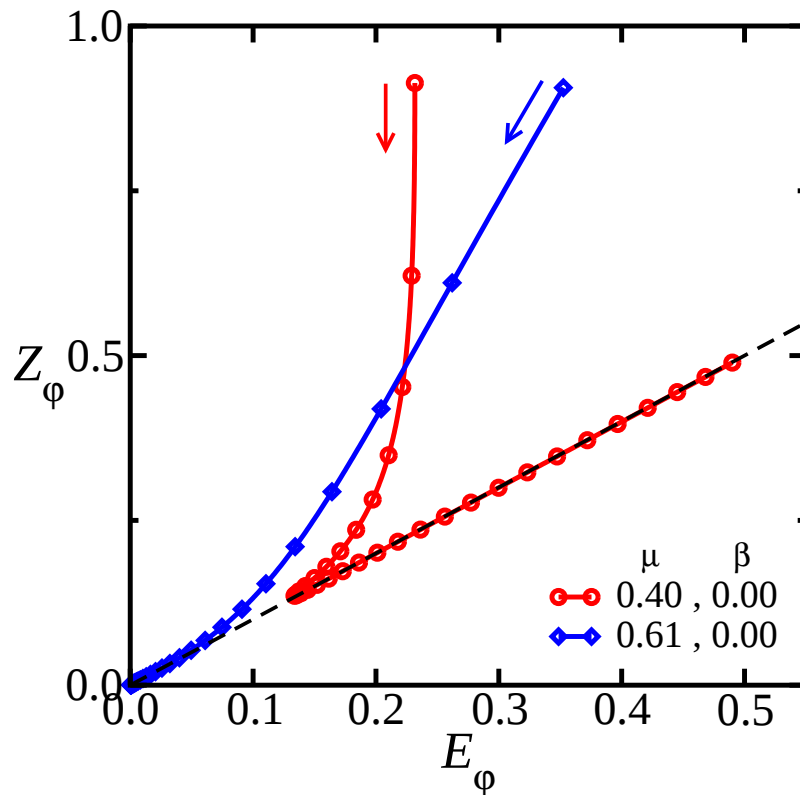
$$E_\varphi(t) - Z_\varphi(t) = e^{-2\mu t} [E_\varphi(0) - Z_\varphi(0)]$$

Energy-Enstrophy Balance

$$E_\varphi(t) - Z_\varphi(t) \rightarrow 0 \quad \text{as} \quad t \rightarrow \infty$$

$$\Phi_{EZ} = \{\varphi \in \Phi \text{ such that } E_\varphi = Z_\varphi\}$$

$\Rightarrow \Phi_{EZ}$ attracts all initial conditions



Optimization with Constraints

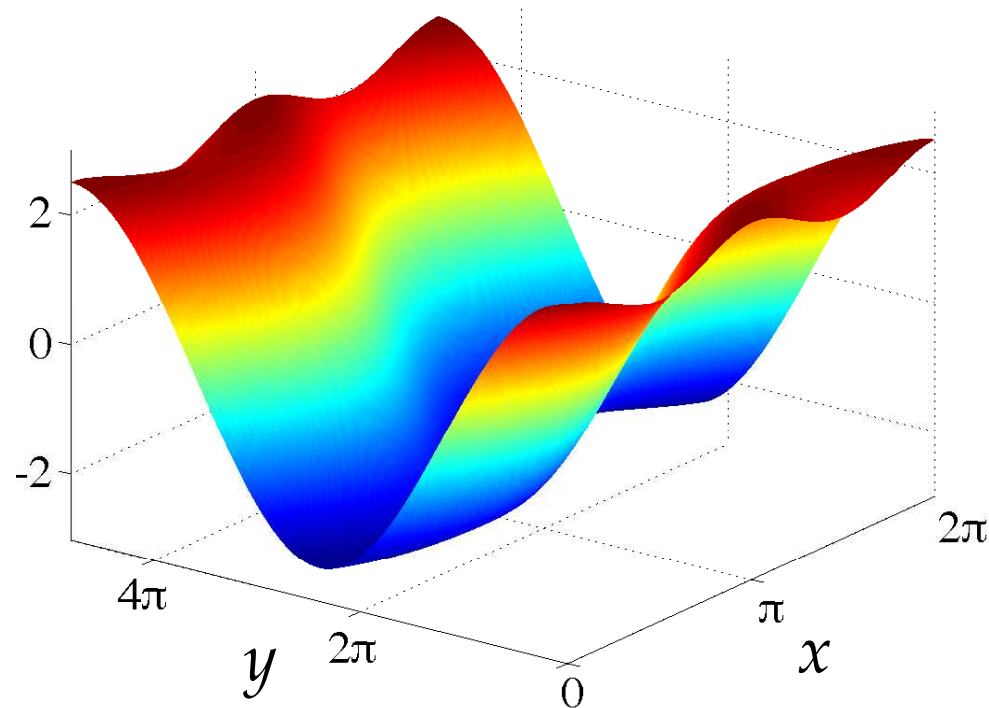
Maximize: $\mathcal{R}[\varphi] \equiv \frac{\langle \varphi_x \varphi_y \cos x \rangle}{\langle |\nabla \varphi|^2 \rangle}$

with constraint $\langle |\nabla \varphi|^2 \rangle = \langle (\nabla^2 \varphi)^2 \rangle$

Optimal solution

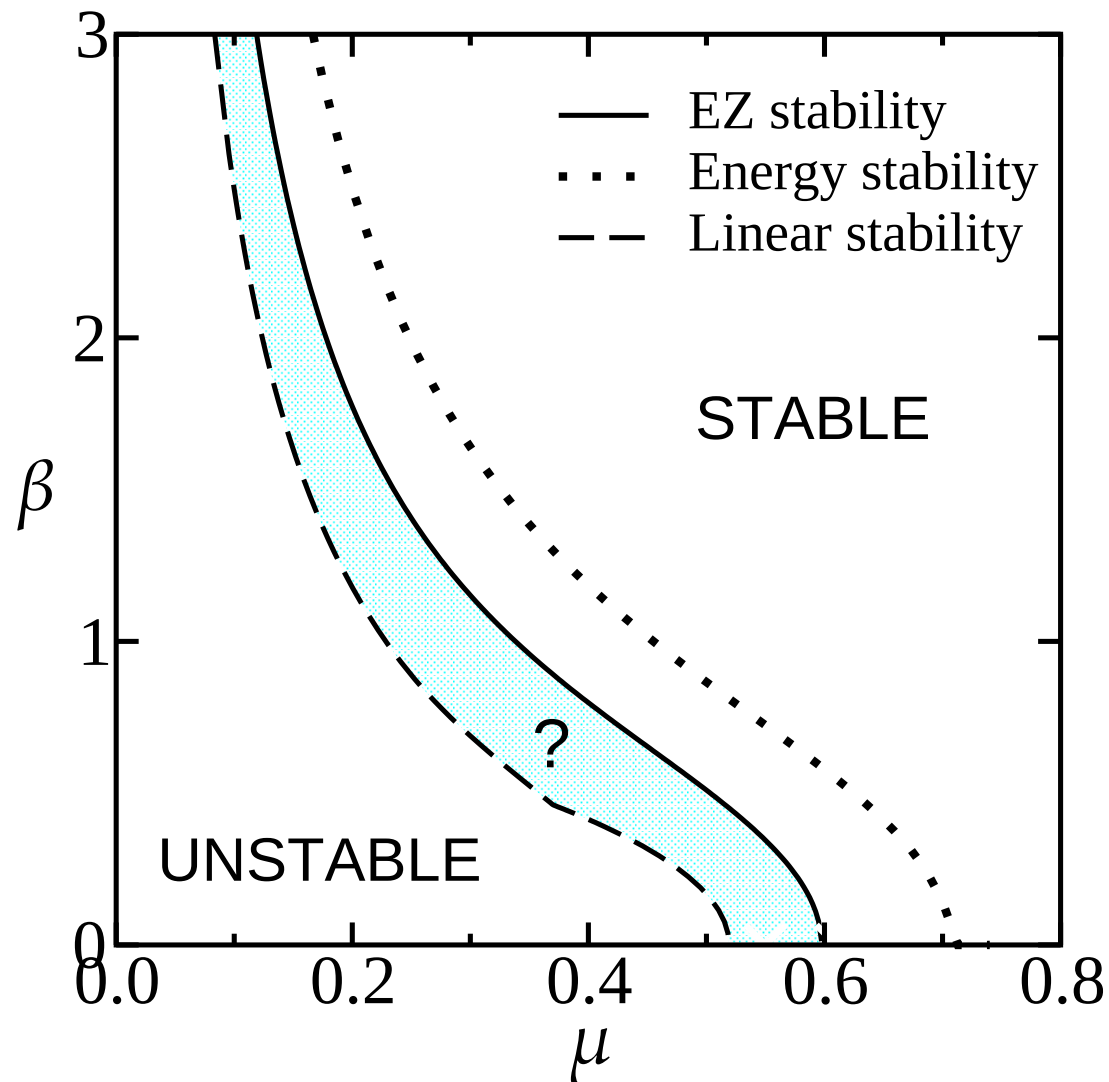
$$\mathcal{R}_* = \mathcal{R}[\varphi_*] = 0.3571$$

$$\varphi_*(x, y) = \Re \left\{ e^{i l y} \tilde{\varphi}(x) \right\} \quad \text{with } l \approx 0.4166$$



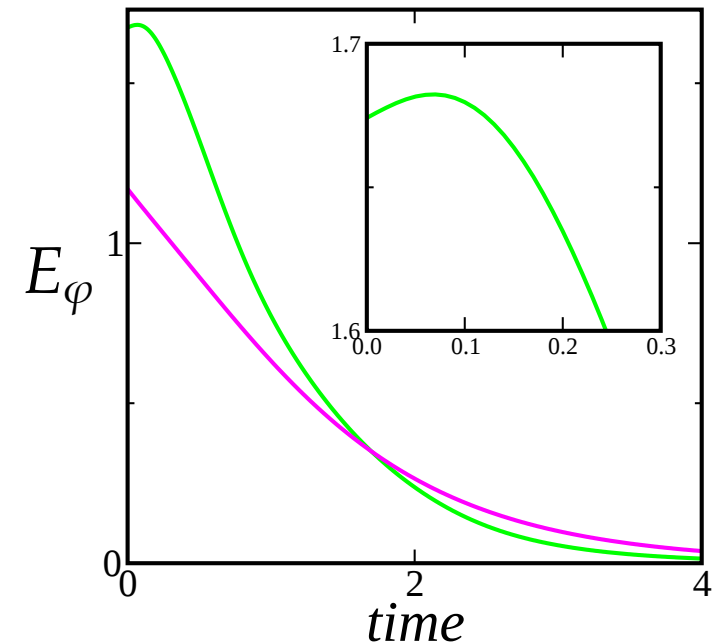
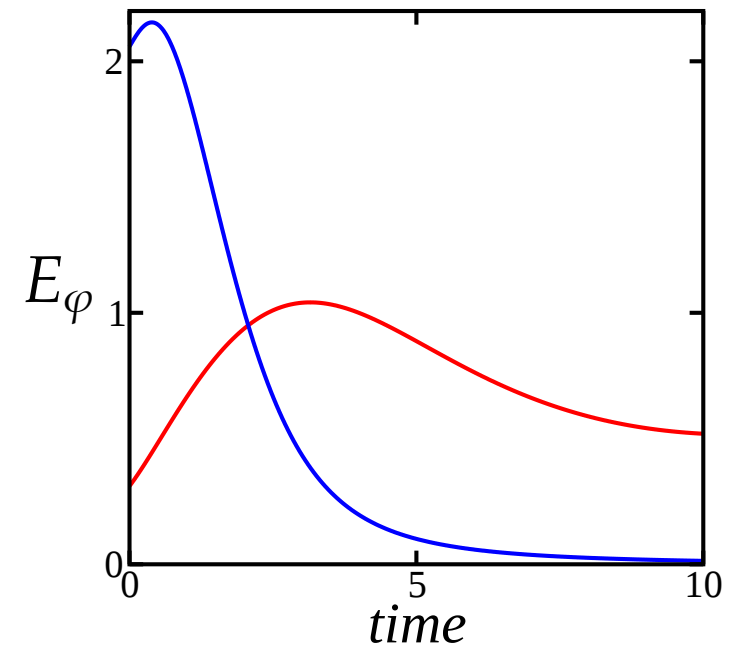
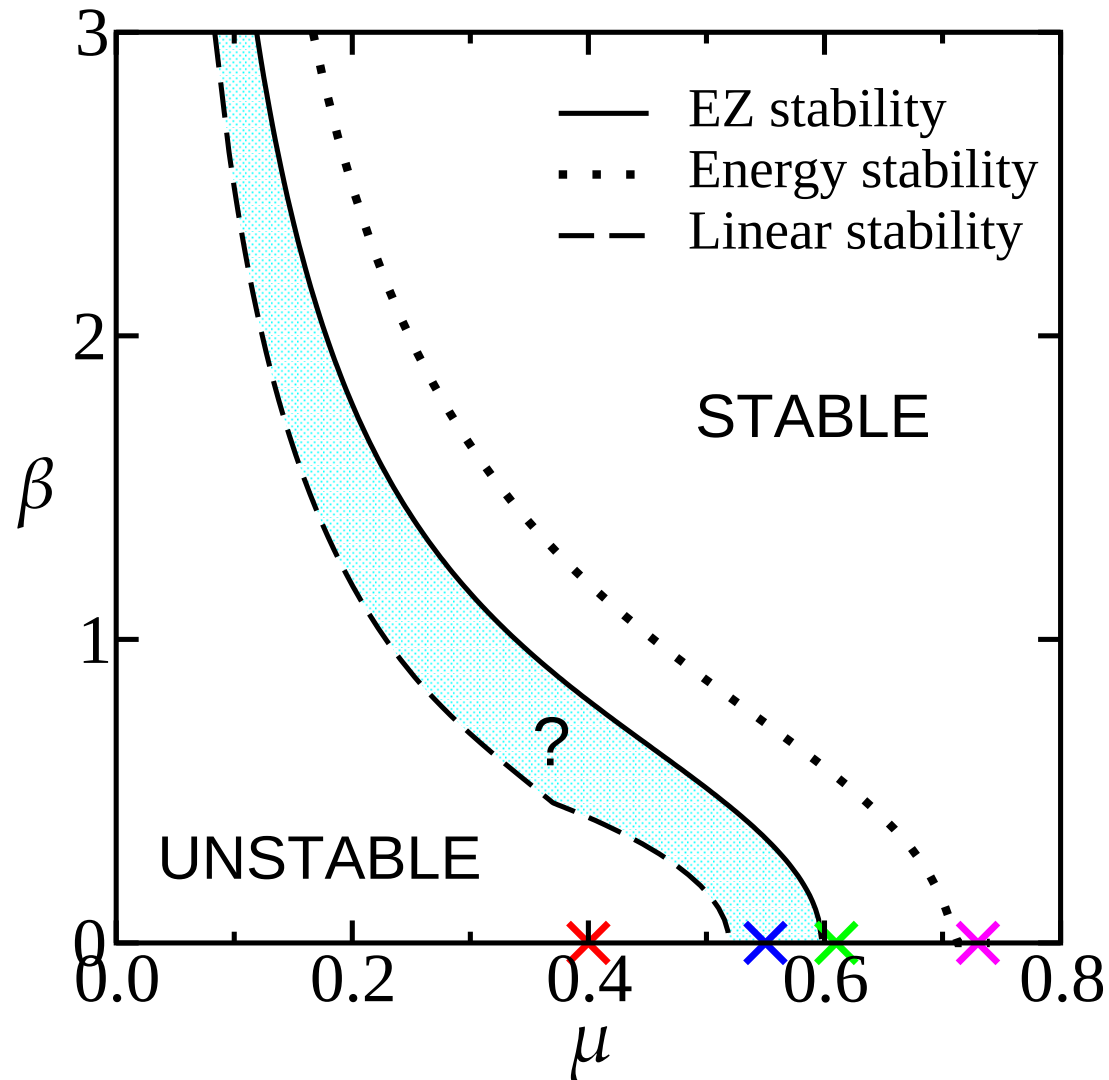
Energy-Enstrophy (EZ) Stability ($\nu = 0$)

$$\beta = \sqrt{\frac{0.13}{\mu^2} - \mu^2} \quad (a = 2.8\mu)$$



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Limitation of the EZ method

The EZ method applies only for

- inviscid flow $\nu = 0$, and
- basic state consists of a single Helmholtz mode:

$$\nabla^2 \psi_L + k_f^2 \psi_L = 0$$

Evolution of perturbation energy and enstrophy:

$$\frac{dE_\varphi}{dt} = -\left\langle \psi_L J(\varphi, \nabla^2 \varphi) \right\rangle - 2\mu E_\varphi + 2\nu Z_\varphi$$

$$\frac{dZ_\varphi}{dt} = \left\langle \zeta_L J(\varphi, \nabla^2 \varphi) \right\rangle - 2\mu Z_\varphi + 2\nu P_\varphi$$

$$P_\varphi = \frac{1}{2} \left\langle |\nabla(\nabla^2 \varphi)|^2 \right\rangle$$

Extended Energy-Enstrophy (EEZ) Stability

Consider a family of norm with the parameter α :

$$Q(\alpha) = (1 - \alpha) E_\varphi + \alpha Z_\varphi, \quad 0 \leq \alpha \leq 1$$

$$\frac{dQ}{dt} = 2 \left\{ \mathcal{R}_Q[\varphi; \alpha, \nu, a] - \mu \right\} Q$$

Global stability : $Q(\alpha) \rightarrow 0$ as $t \rightarrow \infty$ for some α .

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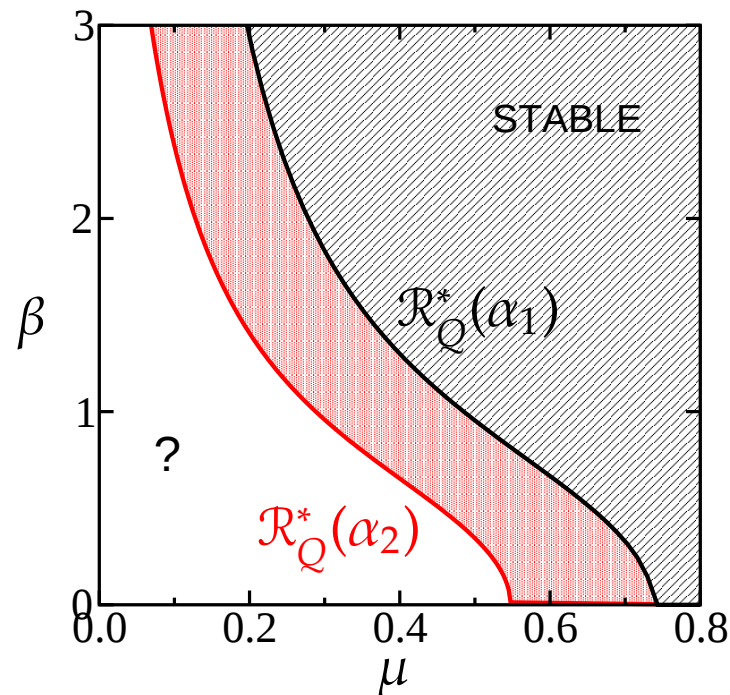
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$$\mathcal{R}_Q^*(\alpha, \nu, a) = \max_{\varphi \in \Phi} \mathcal{R}_Q[\varphi; \alpha, \nu, a]$$

For each α , neutral condition : $\mathcal{R}_Q^*(\alpha, \nu, a) = \mu$



$$\mathcal{R}_Q^*(\alpha_2) < \mathcal{R}_Q^*(\alpha_1)$$

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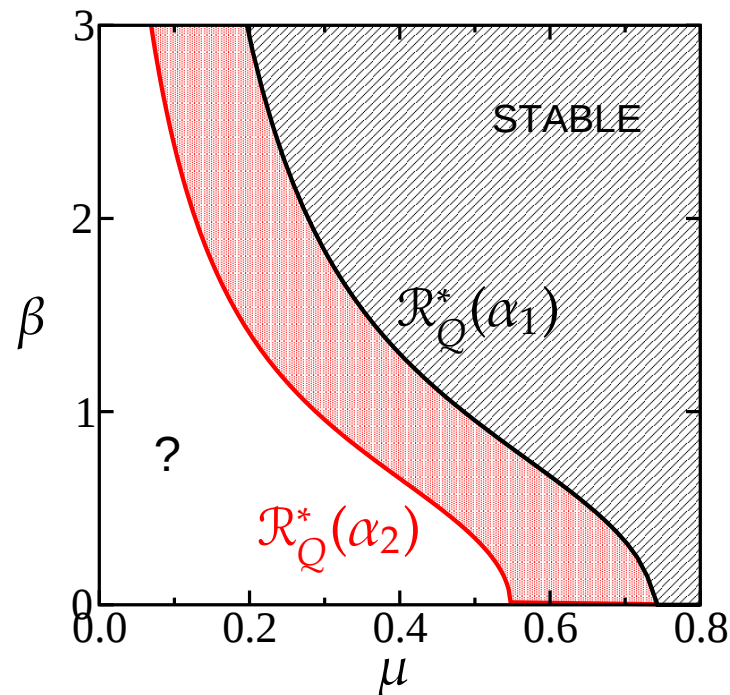
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"Optimal" neutral condition : $\min_{\alpha} \mathcal{R}_Q^*(\alpha, \nu, a) = \mu$

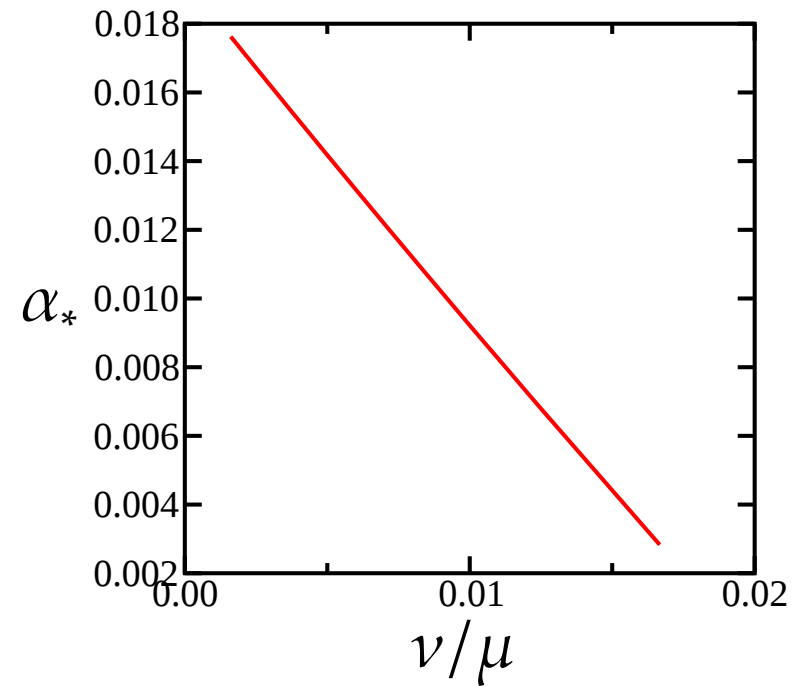
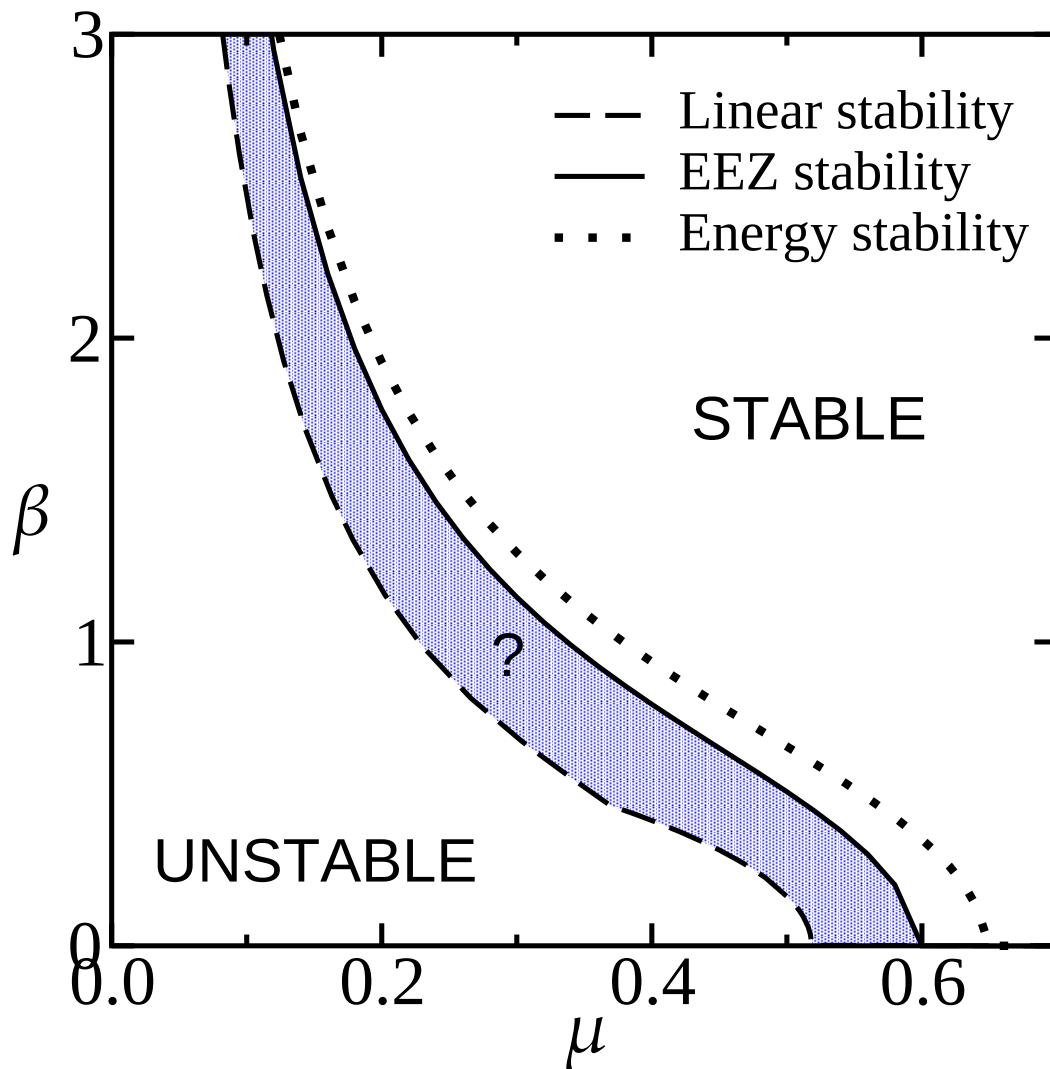


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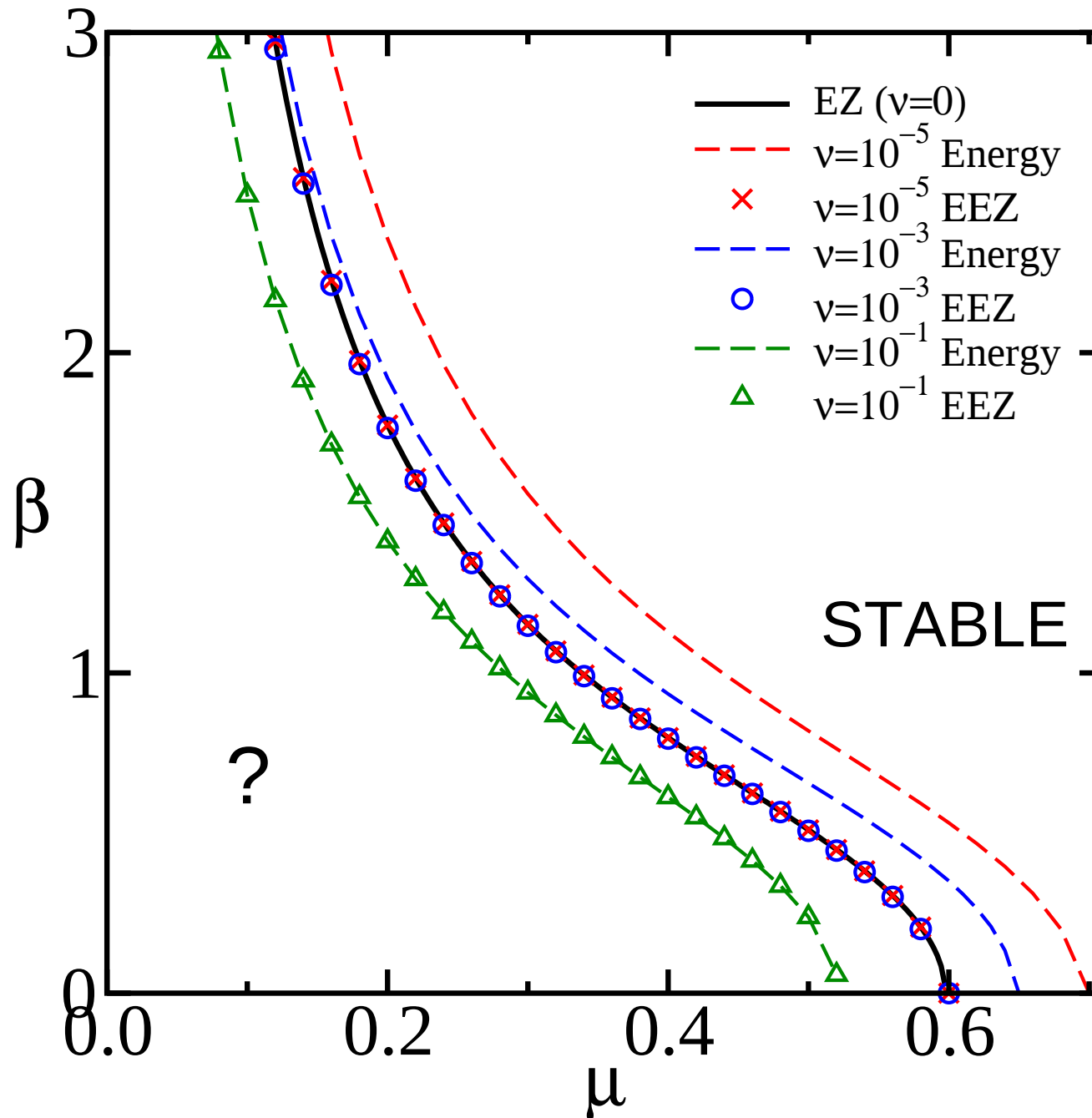
Extended EZ Stability ($\nu = 10^{-3}$)

$$\nabla^2 \psi_t + J(\psi, \nabla^2 \psi) + \beta \psi_x = -\mu \nabla^2 \psi + \cos x + \nu \nabla^2 \zeta$$

$$Q(\alpha) = (1 - \alpha) E_\varphi + \alpha Z_\varphi$$



Extended EZ Stability for different ν



Non-Kolmogorov flows

- multiple Helmholtz modes:

$$\psi_L = -a (\cos x + \delta \sin mx)$$

- a street of counter-rotating vortices,
Mallier-Maslowe solution:

$$\psi_L = \ln \left(\frac{\cosh \varepsilon y - \varepsilon \cos x}{\cosh \varepsilon y + \varepsilon \cos x} \right)$$

Summary

By incorporating information based on the enstrophy, we develop the EZ and EEZ stability method which

- allows transient growth in $E_\varphi(t)$ ($\varphi(t=0) \notin \Phi_{EZ}$)
- identifies a physically realistic most-unstable disturbance
- lies closer to the linear stability neutral curve

