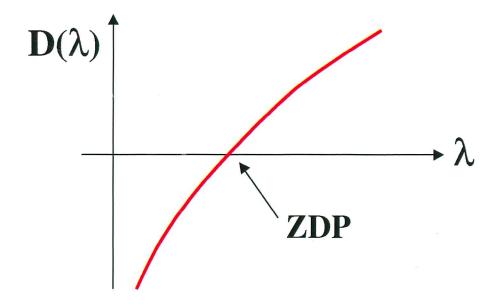
# Long Distance Communication System

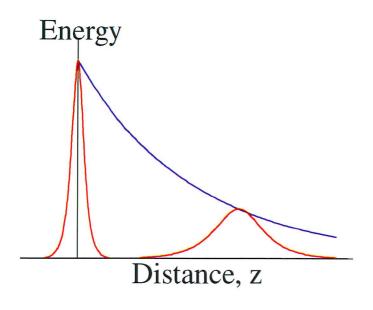
#### NRZ format:

propagate near the zero dispersion point (ZDP)



variation of ZDP by as much as 1 nm (Jopson *et al. Electron. Letts.*, **31**, p.2115, 1995.)

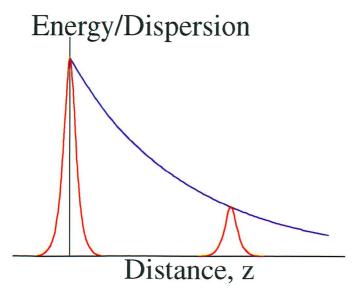
#### **Soliton format:**



#### Standard fiber

$$D(\lambda) = \text{constant}$$

- energy decreases exponentially
- pulse width increases exponentially



## Dispersion decreasing fiber

$$D(\lambda) \sim e^{-\Gamma z}$$

- energy decreases exponentially
- pulse width remains constant

• need to determine the variation of chromatic dispersion along an optical fiber

#### methods proposed recently :

- M. Ohashi et. al., Electron. Lett., 29, p.426, 1993.
  - estimated from mode-field diameter
- S. Nishi et. al., Electron. Lett., 31, p.225, 1995.
  - based on modulated-instability-induced-gain
- R. Jopson et. al., Electron. Lett., 31, p.2115, 1995.
  - phase-matching condition in four wave mixing
- L. Mollenauer, Opt. Lett., 21, p.1724, 1996.
  - four wave mixing

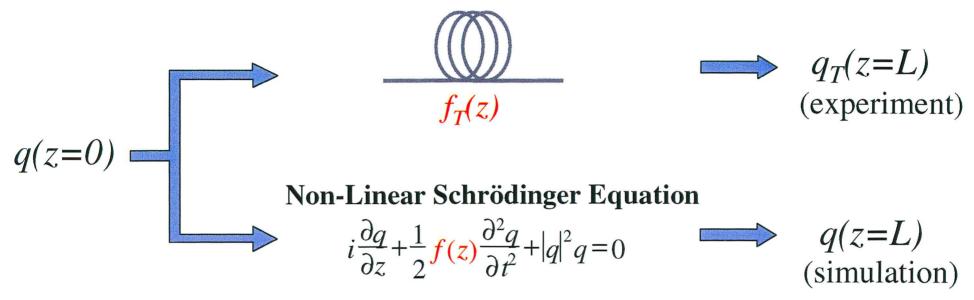
#### **Current Method**

- output waveform carries information about the fiber
- determine fiber dispersion from a theoretical model of signal propagation in fiber

## **Advantage**

• can be used to determine other fiber parameters if a suitable model is used

## Theory and Algorithm



- **1** Guess f(z)
- **2** Calculate q(z=L)
- 3 Compare q(z=L) and  $q_T(z=L)$ ; adjust f(z) accordingly
- **4** Repeat step **1** through **3** until  $f(z) \sim f_T(z)$

# How to choose $\Delta f$ ?

• Define an error function :  $E[q(L,t), q_T(L,t)]$ 

e.g. 1. 
$$E(q, q_T) = \int |q(L) - q_T(L)|^2 dt$$

2. 
$$E(q, q_T) = \int ||q(L)|^2 - |q_T(L)|^2|^2 dt$$

Expand

$$f(z) = \sum_{\mu=1}^{N} f_{\mu} \psi_{\mu}(z)$$

 $\psi_{\mu}$ : orthogonal function

$$\Delta E = \sum_{\mu=1}^{N} \frac{dE}{df_{\mu}} \Delta f_{\mu}$$

Choose 
$$\Delta f_{\mu} = -\alpha \frac{dE}{df_{\mu}}$$

$$\Delta E = -\alpha \sum_{\mu=1}^{N} \left( \frac{dE}{df_{\mu}} \right)^{2} < 0$$
 Gradient Descent!

$$\frac{dE}{df_{\mu}} = \int \left( \frac{\delta E}{\delta q} \frac{\partial q}{\partial f_{\mu}} + \frac{\delta E}{\delta q^{*}} \frac{\partial q^{*}}{\partial f_{\mu}} \right) dt$$

and  $\frac{\partial q}{\partial f_{\mu}}$ ,  $\frac{\partial q^*}{\partial f_{\mu}}$  satisfy the linearized non-linear

Schrödinger equation:

$$i\frac{\partial \varphi}{\partial z} + \frac{1}{2}f(z)\frac{\partial^2 \varphi}{\partial t^2} + 2|q|^2\varphi + q^2\varphi^* = -\frac{1}{2}\frac{\partial f}{\partial f_{\mu}}\frac{\partial^2 q}{\partial t^2}$$

 $\Delta f$  can be determined from given q(z=L) and  $q_T(z=L)$ 

- 1 The convergence of gradient descent algorithm is too slow, we use conjugated gradient instead.
- 2 In feasibility test,  $f_T(z)$  is also generated from the non-linear Schrödinger equation

## **Results**

### **Without Loss**

Target profile:

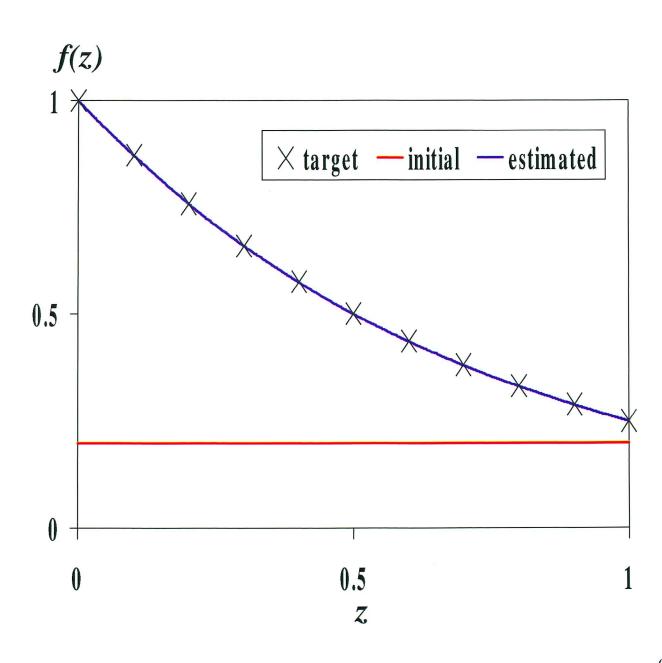
$$f_T(z) = \exp[(\ln 0.25) z]$$

initial guess:

$$f(z) = 0.2$$

input pulse:

$$\frac{0.5}{\sqrt{\sqrt{\pi}}}e^{-\frac{t^2}{2}}$$



# With Loss (Γ=0.69)

Target profile:

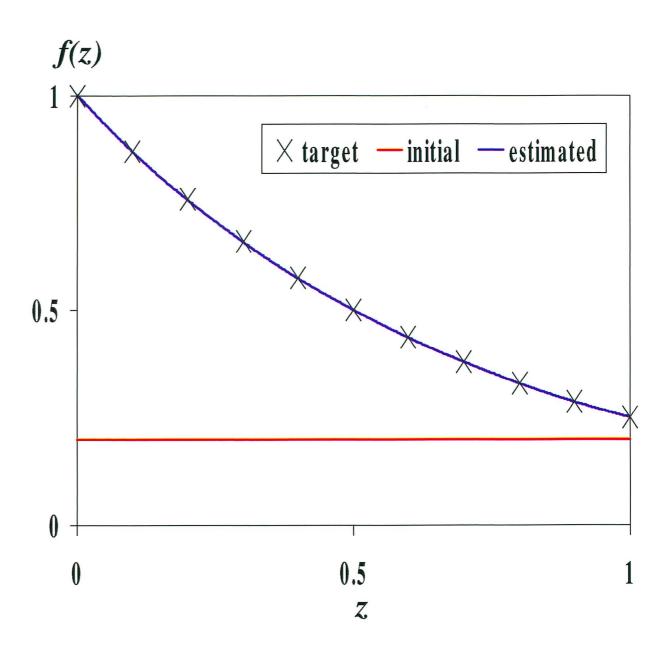
$$f_T(z) = \exp[(\ln 0.25) z]$$

initial guess:

$$f(z) = 0.2$$

input pulse:

$$\frac{1.5}{\sqrt{\sqrt{\pi}}}e^{-\frac{t^2}{2}}$$



## With Loss and 3rd order dispersion

 $(\Gamma=0.69, \beta=1)$ 

Target profile:

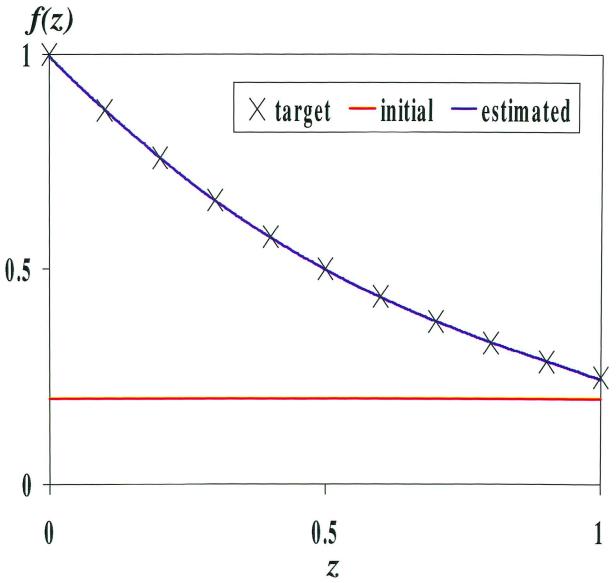
$$f_T(z) = \exp[(\ln 0.25) z]$$

initial guess:

$$f(z) = 0.2$$

input pulse:

$$\frac{1.5}{\sqrt{\sqrt{\pi}}}e^{-\frac{t^2}{2}}$$



## Summary

Reconstruction of the dispersion profile from an input output pulse profile

# **Further Study**

- Effects of timing jitters and amplitude jitters
- Experimental verification