

Probabilistic parametrization of condensation in coarse-grained moisture transport models

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Funded by the EPSRC network

Research on Changes of Variability and Environmental Risk (ReCoVER)

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Condensation of water vapour

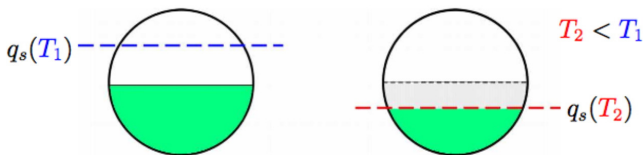
- specific humidity of an air parcel:

$$Q = \frac{\text{mass of water vapor}}{\text{total air mass}}$$

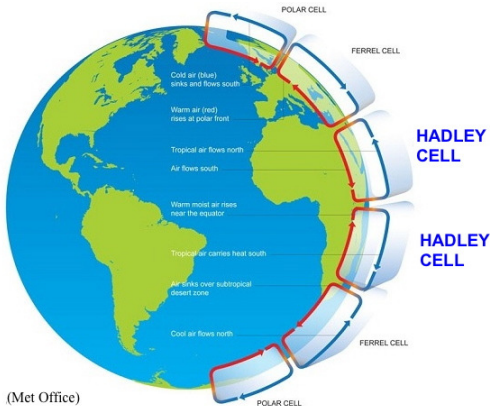
- saturation specific humidity, $q_s(T)$

$$Q = \begin{cases} q_s & \text{if } Q > q_s \text{ (excessive moisture condensed)} \\ Q & \text{otherwise} \end{cases}$$

- $q_s(T)$ decreases with temperature T , hence generally decreases with height



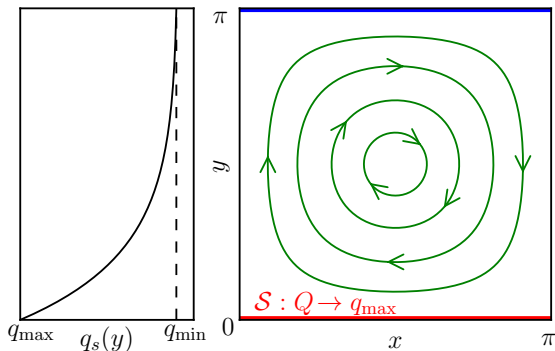
Moisture transport in the atmosphere



- water vapour enters the atmosphere by evaporation from surface
- large-scale circulation, e.g. the Hadley cell:
 - moisture converges toward the Tropics, then rises and condensed
 - dry air moves poleward and subside near the sub-tropics
- small-scale flow: mixing between moist and dry air

Advection–condensation model

- bounded domain: $[0, \pi] \times [0, \pi]$, **reflective** boundaries
- $q_s(y) = q_{\max} \exp(-\alpha y)$: $q_s(0) = q_{\max}$ and $q_s(\pi) = q_{\min}$
- **resetting source**: $Q = q_{\max}$ if parcel hits $y = 0$
- large-scale **cellular flow**: $\psi = \sin x \sin y$; $(u, v) = (-\psi_y, \psi_x)$
- small-scale **turbulence**: Brownian motion



Lagrangian versus Eulerian formulation

- Stochastic Lagrangian approach
 - consider an ensemble of moist parcels
 - position and specific humidity of individual parcel described by the **random variables** (Q, X, Y)
 - **stochastic differential equations** governing the evolution of (Q, X, Y)
- Deterministic Eulerian approach
 - specific humidity described by a **coarse-grained field** $q(x, y, t)$
 - evolution of $q(x, y, t)$ governed by a **partial differential equation**

These two approaches give very different results!

Lagrangian particle formulation

$$dX(t) = u(X, Y) dt + \sqrt{2\kappa} dW_1(t)$$

$$dY(t) = v(X, Y) dt + \sqrt{2\kappa} dW_2(t)$$

$$dQ(t) = [\textcolor{red}{S}(Y) - \textcolor{blue}{C}(Q, Y)] dt$$

$$\psi = -\sin x \sin y$$

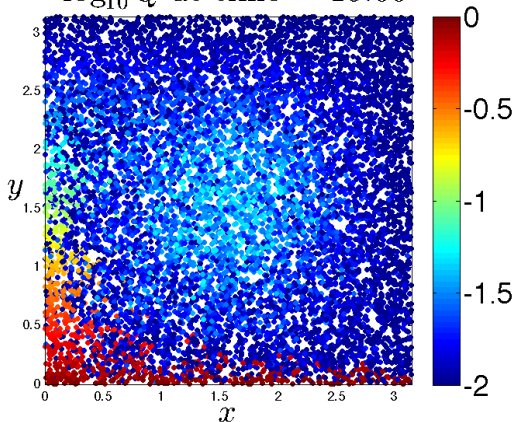
$$u = -\psi_y$$

$$v = \psi_x$$

$$\kappa = 10^{-2}$$

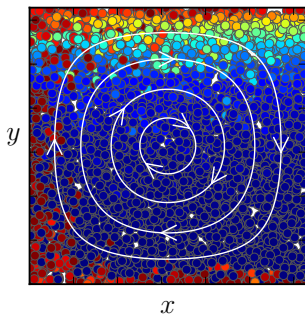
fast condensation $\textcolor{blue}{C} : Q \rightarrow \min[Q, q_s(Y)]$

$\log_{10} Q$ at time = 15.00

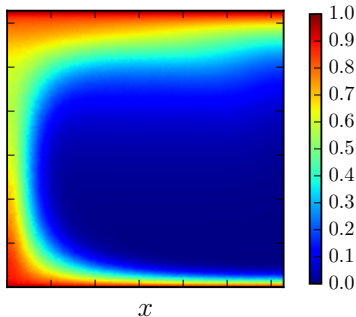


Lagrangian model: relative humidity

snapshot of parcels



“Observed” $q_{\text{bin}}(x, y)$



$$\text{Relative humidity} = \frac{Q}{q_s(Y)}$$

- **Observation:** divide the domain into small bins and average over parcels in each bin to get the field $q_{\text{bin}}(x, y)$

Eulerian field formulation

Weather/climate models: moisture field $q(x, y, t)$ governed by a PDE, the advection–condensation–diffusion equation:

$$\frac{\partial q}{\partial t} + \vec{u} \cdot \nabla q = \kappa \nabla^2 q + \textcolor{red}{S} - \textcolor{blue}{C}$$

- κ : eddy diffusivity representing subgrid-scale turbulence (molecular diffusion neglected)

Eulerian field formulation

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$$\frac{\partial q}{\partial t} + \vec{u} \cdot \nabla q = \kappa \nabla^2 q - C$$

● **boundary source:** $q(x, y = 0, t) = q_{\max}$

Eulerian field formulation

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$$\frac{\partial q_*}{\partial t} + \vec{u} \cdot \nabla q_* = \kappa \nabla^2 q_*$$

$$C : q(x, y, t) \rightarrow \min[q_*(x, y, t), q_s(y)]$$

● **boundary source:** $q(x, y = 0, t) = q_{\max}$

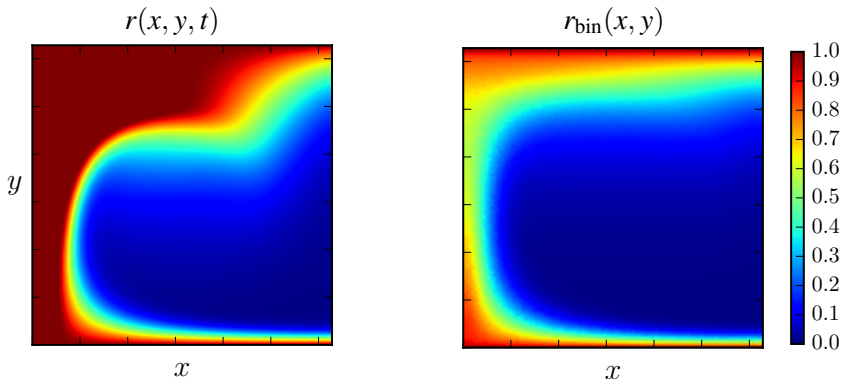
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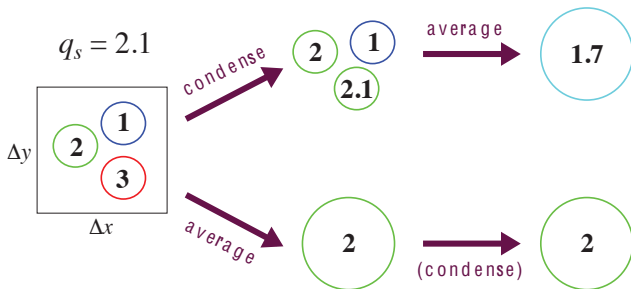
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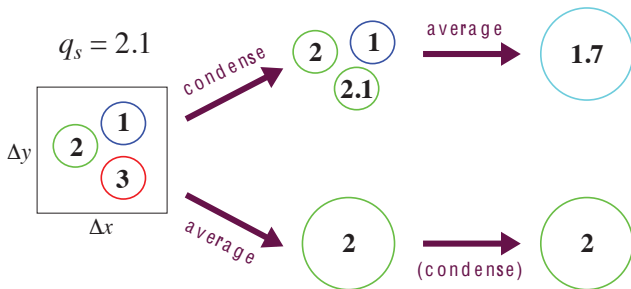
Why are PDE models so wet?

The coarse-graining process and the condensation process do not commute:



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Question: How do we improve a PDE model? Can we put back some subgrid-scale fluctuation in the condensation term?

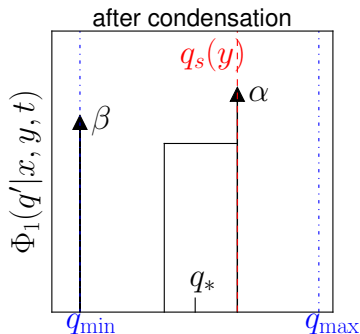
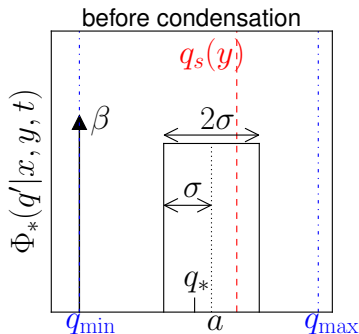
Condensation parametrization

$$\frac{\partial q_*}{\partial t} + \vec{u} \cdot \nabla q_* = \kappa \nabla^2 q_*$$

$$C : q(x, y, t) \rightarrow \min[q_*(x, y, t), q_s(y)]$$

after advection–diffusion steps, imagine there is a distribution $\Phi_*(q'|x, y, t)$:

$$q_* = \int q' \Phi_*(q'|x, y, t) dq'$$



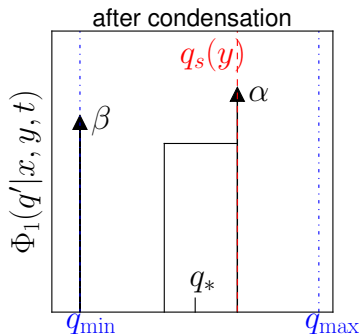
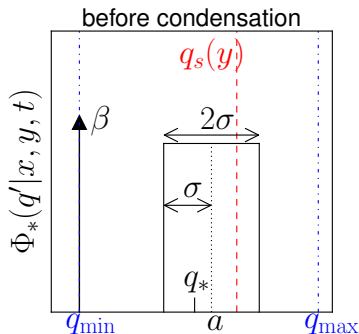
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- fast condensation over the distribution Φ_* to gives $\Phi_1(q'|x, y, t)$



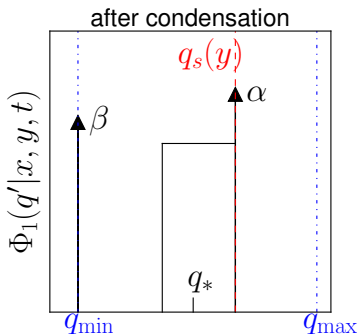
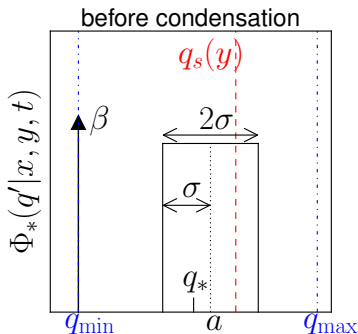
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- fast condensation over the distribution Φ_* to gives $\Phi_1(q'|x, y, t)$
- $q(x, y, t + \Delta t) = \int q' \Phi_1(q'|x, y, t) dq'$

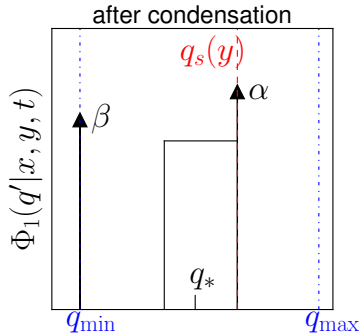
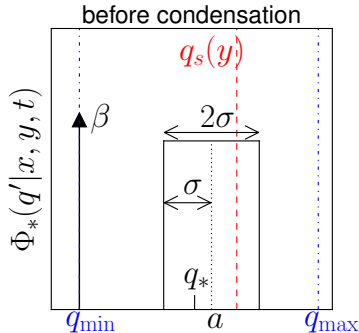


Method of assumed PDF: shape of Φ_*

- To implement the parametrization, need to fix the shape of Φ_*
- For our idealised overturning cell:

$$\Phi_*(q'|x, y, t) = \beta(x, y, t)\delta(q - q_{\min}) + \tilde{\Phi}_*(q'|x, y, t)$$

with three parameters (β, a, σ)



Determination of the PDF parameters

- The dry spike, β

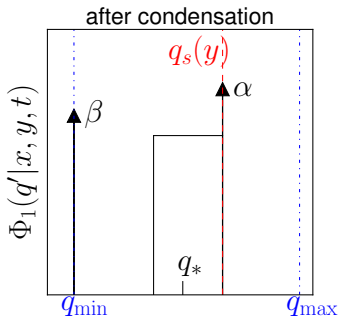
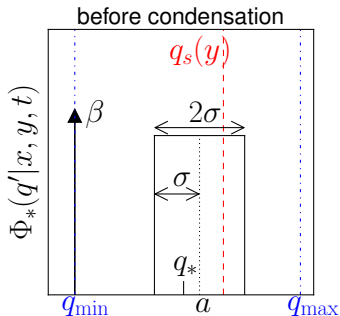
$$\partial_t \beta + \vec{u} \cdot \nabla \beta = \kappa \nabla^2 \beta, \quad \beta(x, 0, t) = 0, \quad \beta(x, \pi, t) = 1$$

- The location, a

$$q_* = \int q' \Phi_*(q'|x, y, t) dq' \Rightarrow a = \frac{q_* - \beta q_{\min}}{1 - \beta}$$

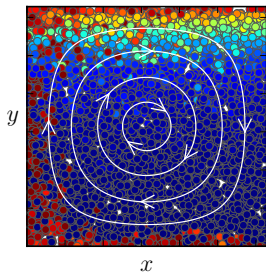
- The width, σ

- fixed empirically “by hand”
- considering the second moment of q' (additional computation)

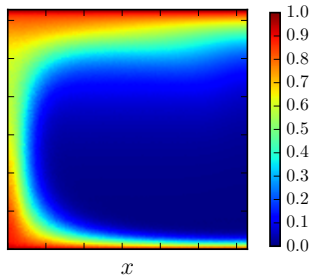


Results: relative humidity

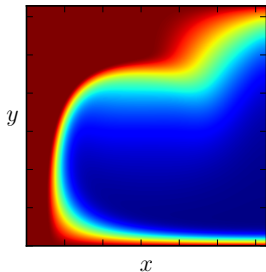
snapshot of parcels



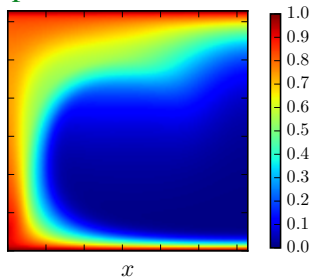
$q_{\text{bin}}(x, y)$



PDE



parametrized PDE



Mathematics of the parametrization scheme

- Recall (Q, X, Y) are governed by a set of SDEs
 $\Rightarrow$ the joint PDF $P(q, x, y; t)$ satisfies the Fokker-Planck equation:

$$\frac{\partial P}{\partial t} + \vec{u} \cdot \nabla P - \frac{\partial}{\partial q}(CP) = \kappa \nabla^2 P$$

- $q_{\text{bin}}(x, y, t) \approx \bar{q}(x, y, t) = \int_{q_{\min}}^{q_{\max}} q' \hat{P}(q'|x, y; t) \, dq'$

$$\frac{\partial \bar{q}}{\partial t} + \vec{u} \cdot \nabla \bar{q} = \kappa \nabla^2 \bar{q} - \int_{q_{\min}}^{q_{\max}} C(q', q_s) \hat{P}(q'|x, y; t) \, dq'$$

- The coarse-grained field

$$\frac{\partial q}{\partial t} + \vec{u} \cdot \nabla q = \kappa \nabla^2 q - C(q, q_s)$$

- Parametrized condensation

$$\frac{\partial q}{\partial t} + \vec{u} \cdot \nabla q = \kappa \nabla^2 q - \int_{q_{\min}}^{q_{\max}} C(q', q_s) \Phi_*(q'|x, y; t) \, dq'$$