

Protein identification using mass spectrometry data and the case of the glass slipper

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and

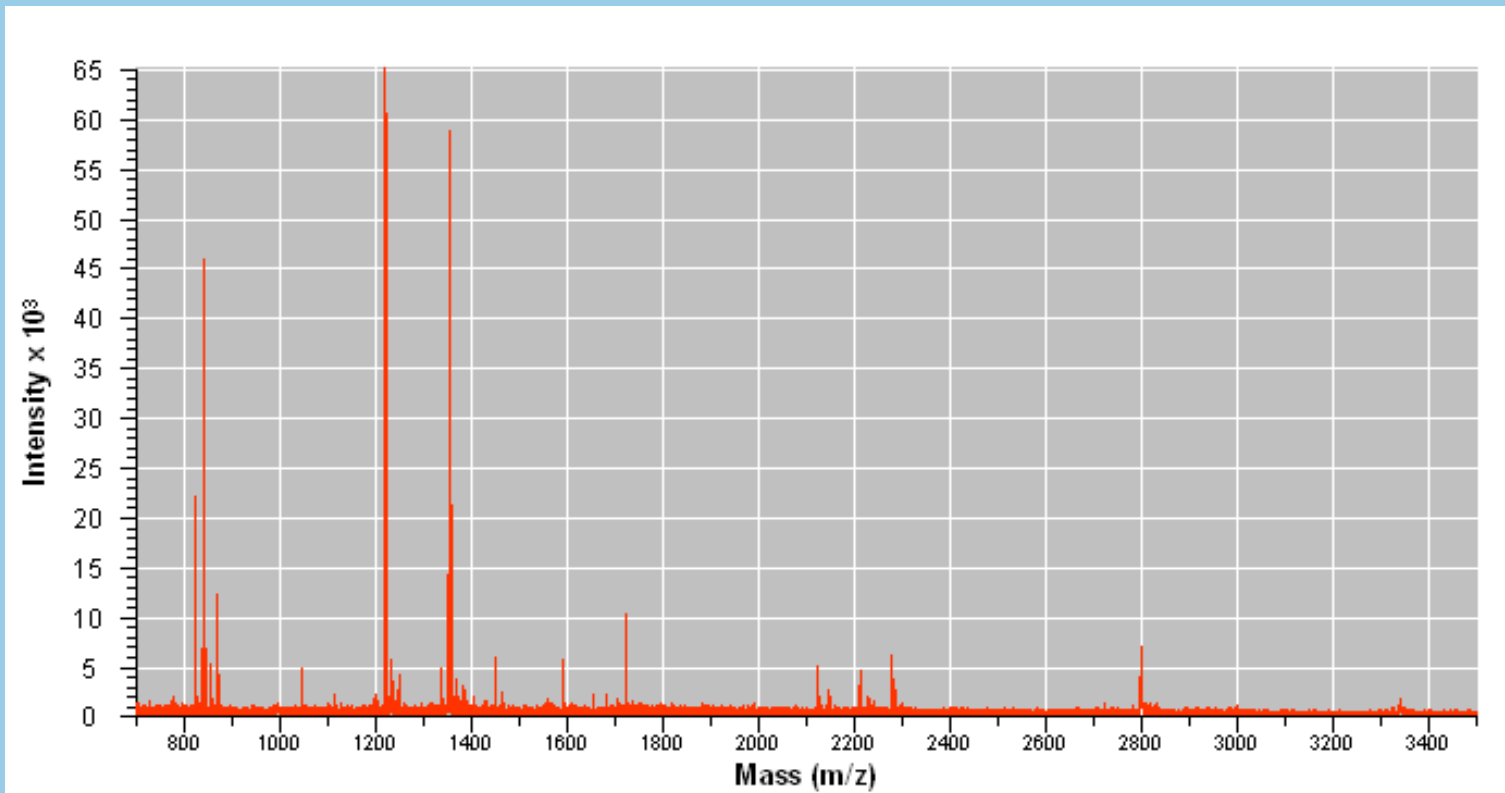
Gavin Hope
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Key reference

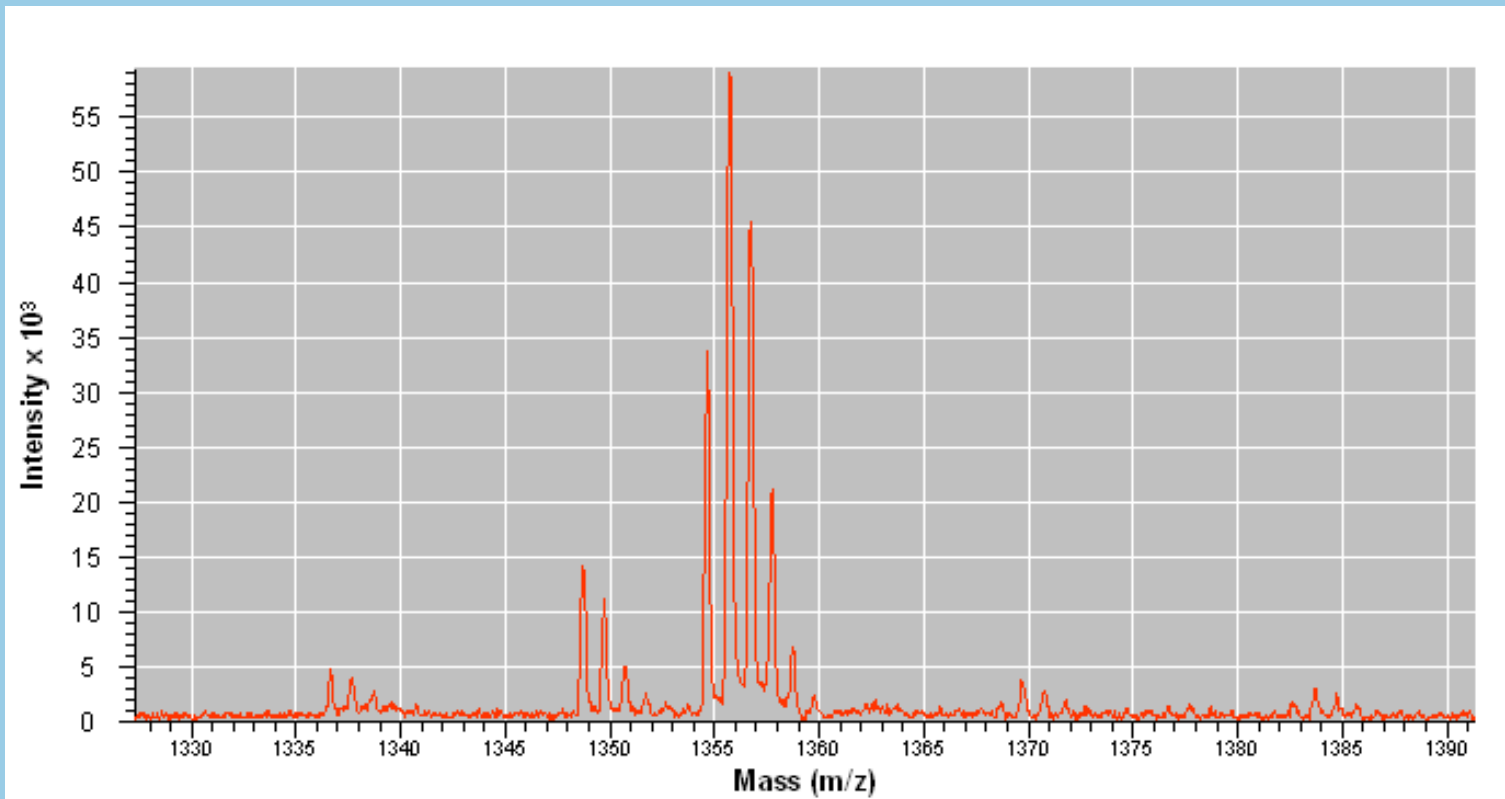
Grimm, J.L.C. and Grimm, W.C., 1857, *Kinder- und Hausmärchen* (Children's and Household Tales), 7th Edition.

1. Protein identification from a Bayesian viewpoint.
2. Complications and difficulties.
3. Review of some available algorithms.
4. Dealing with the difficulties.
5. The “glass (or golden!) slipper” problem.

Picture of a spectrum.



Close-up of a spectrum.



General Principle

- Sample of some unidentified protein k^* .
- Database $S = \{k_1, \dots, k_n\}$ of known proteins.
- Prior probability that $k^* = k_i$ is $p_i^{(0)}$.

$$\Pr(k^* = k_i | y) = p_i^{(1)} = \frac{p_i^{(0)} L_{yi}}{\sum_{j=1}^n p_j^{(0)} L_{yj}}. \quad (1)$$

Application to the protein problem

- For the sample we have a set P_y of n_y observed peaks.
- For each k_i we have a set P_i of n_i theoretical peaks.
- Let $n_{yi} = \min\{n_y, n_i\}$. The number of possible allocations is

$$N_{yi} = \sum_{m=0}^{n_{yi}} \frac{n_y! n_i!}{m! (n_y - m)! (n_i - m)!}.$$

- The likelihood is

$$L_{yi} = \sum_{j=1}^{N_{yi}} \Pr(a_{yij} | k_i = k^*) \Pr(P_y | k_i = k^*, a_{yij}). \quad (2)$$

Complications and difficulties

- “Noise” .
- Location shifts of peaks.
- Theoretical peaks might not appear. (Missed cleavage, obscured by noise, not ionised etc.)
- Unexpected peaks might appear. (E.g. contamination, modifications).

Some algorithms

- Probabilistic
- Other

“Probabilistic”

- “MOWSE” (Pappin, Højrup and Bleasby, 1993)
- “Mascot” (Perkins, Pappin, Creasy and Cottrell, 1999)
- “MSROFIT” (Berndt, Hobohm and Langen, 1999)
- “ProFound” (Zhang and Chait, 2000)

Other

- “PepSea” (Mann, Højrup and Roepstorff, 1993)
- “PeptIdent” / “Multident” (Wilkins *et al.*, 1998, 1999)
- “PeptIdent2” (Gras *et al.*, 1999)

See also, e.g., Fenyö (2000)

What probabilities?

- *Cf.* forensic DNA database search problem. E.g. Balding (2002).
- – Posterior $\Pr(k^* = k_i \mid y)$.
 - Probability, given y , that we will find a “match” in the database “by chance.”
 - * “significance”
 - * “false positive probability”

- $Pr(y \mid k^* = k_i)$ or $Pr(\text{“match”} \mid y)$.
- $Pr(k^* \notin S)$. See later.

Plug-in probabilities

Example: Given θ ,

$$p = \Pr(\text{peak appears} \mid \theta) = \theta.$$

$$\theta \sim \text{beta}(a, b)$$

One peak:

$$p = \int_0^1 \theta f(\theta) d\theta = \frac{a}{a+b}.$$

Two peaks:

$$\int_0^1 \theta^2 f(\theta) d\theta = \left(\frac{a}{a+b} \right) \left(\frac{a+1}{a+b+1} \right) > p^2.$$

Sequence of x appearances and $n - x$ non-appearances:

$$\begin{aligned} p_n(x) &= \int_0^1 \theta^x (1 - \theta)^{n-x} f(\theta) d\theta \\ &= \frac{\Gamma(a+b) \Gamma(a+x) \Gamma(b+n-x)}{\Gamma(a) \Gamma(b) \Gamma(a+b+n)} \\ &= \frac{C(a, x) C(b, n-x)}{C(a+b, n)} \end{aligned}$$

$$p_n(x) = \frac{C(a, x)C(b, n - x)}{C(a + b, n)} \quad (3)$$

where

$$C(a, x) = a(a + 1) \cdots (a + x - 1)$$

$$C(b, n - x) = b(b + 1) \cdots (b + n - x - 1)$$

$$C(a + b, n) = (a + b)(a + b + 1) \cdots (a + b + n - 1)$$

Dealing with the difficulties

- Peak extraction
- Appearance of predicted peaks
- Location shifts of observed peaks
- Appearance of extra peaks

$$\begin{aligned} \Pr(a_{yij} \mid k_i = k^*) &= \Pr[b(a_{yij}) \mid k = k^*] \\ &\quad \times \Pr[c_y(a_{yij}) \mid k_i = k^*] \end{aligned}$$

$b(a_{yij})$: exactly the selection of species from P_i required by the allocation a_{yij} appears. See (3).

$\Pr[c_y(a_{yij}) \mid k_i = k^*]$: the probability density for the observed peaks appearing in their observed locations, given the allocation a_{yij} .

Location shifts

D_m

Model 1.

$$\mathrm{E}(D_m) = 0$$

$$\mathrm{var}(D_m) = \sigma_c^2 + \sigma_e^2$$

$$\mathrm{covar}(D_m, D_{m'}) = \sigma_c^2$$

Model 2.

Internal calibration at two masses, c_1, c_2 .

Two theoretical masses, m, m' .

$$c_1 < m, \quad m' < c_2$$

Adjustments A_1, A_2 made at masses c_1, c_2 .

Adjustment made at m :

$$\frac{A_1(c_2 - m) + A_2(m - c_1)}{c_2 - c_1}$$

but A_1, A_2 have error – assume independent here.

D_m is adjustment error plus error specific to m .

$$\text{var}(D_m) = C(m, m)\sigma_c^2 + \sigma_e^2$$

$$\text{covar}(D_m, D_{m'}) = C(m, m')\sigma_c^2$$

$$C(m, m) = \frac{(c_2 - m)^2 + (m - c_1)^2}{(c_2 - c_1)^2}$$

$$C(m, m') = \frac{(c_2 - m)(c_2 - m') + (m - c_1)(m' - c_1)}{(c_2 - c_1)^2}$$

Models 3, 4

(May have to transform masses).

Theoretical mass	Observed mass	Calibration masses
t_i	z_i	$c_1 < \dots < c_s$

Also $c_0 \equiv 0$ (usually).

Theoretical masses may be

$$c_j < t_i < c_{j+1} \quad c_s < t_i$$

Model 3

Before calibration:

$$z_i \sim N(t_i, t_i\sigma_c^2 + \sigma_e^2)$$

$$\text{covar}(z_i, z_j) = \sigma_c^2 \min(t_i, t_j)$$

Similarly obs. values for calibration masses.

Condition on observations of calibration masses.

Model 4.

$$z_i \sim \text{gamma}(t_i \lambda, \lambda) \quad (\lambda > 0)$$

$$\text{E}(z_i) = t_i$$

$$z_2 - z_1 \sim \text{gamma}([t_2 - t_1] \lambda, \lambda) \quad (t_1 < t_2)$$

Joint density of obs. masses (inc. calib. masses).

$$\prod_{i=1}^n \left\{ \frac{\lambda^{w_i} (z_i - z_{i-1})^{w_i-1} e^{-\lambda(z_i - z_{i-1})}}{\Gamma(w_i)} \right\} \quad (4)$$

$$w_i = (t_i - t_{i-1})\lambda \quad t_0 \equiv z_0 \equiv 0$$

Condition on calibration masses – divides mass range into intervals.

For $t_i > c_s$ use (4).

For $c_j < t_{h+1}, \dots, t_{h+n} < c_{j+1}$: Dirichlet

$$\frac{\prod_{i=1}^{n+1} \tilde{z}_i^{w_i-1} \Gamma(\sum_{i=1}^{n+1} w_i)}{\prod_{i=1}^{n+1} \Gamma(w_i)}$$

$$\begin{aligned} w_i &= (t_{h+i} - t_{h+i-1})\lambda & z_h &\equiv c_j & T &= c_{j+1} - c_j \\ \tilde{z}_i &= (z_{h+i} - z_{h+i-1})/T & z_{h+n+1} &\equiv c_{j+1} \end{aligned}$$

(Does not allow obs. error).

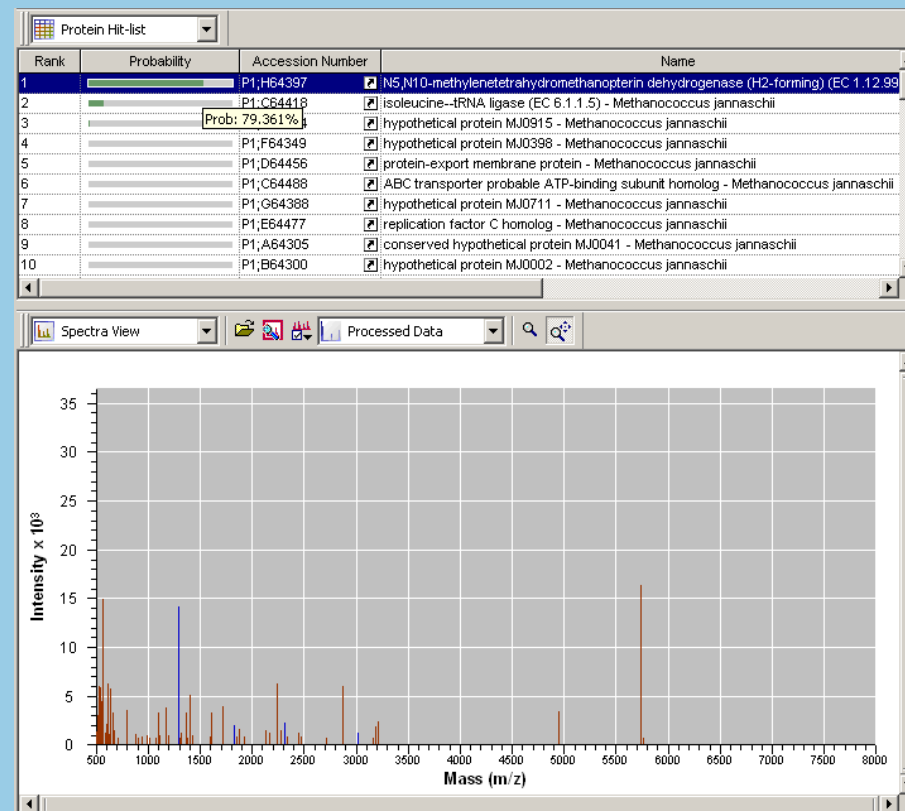
“Extras”

$$\Pr(P_y \mid k_i = k^*, a_{yij}, \lambda_q) = e^{-\lambda_q r} \lambda_q^{q_{yij}}. \quad (5)$$

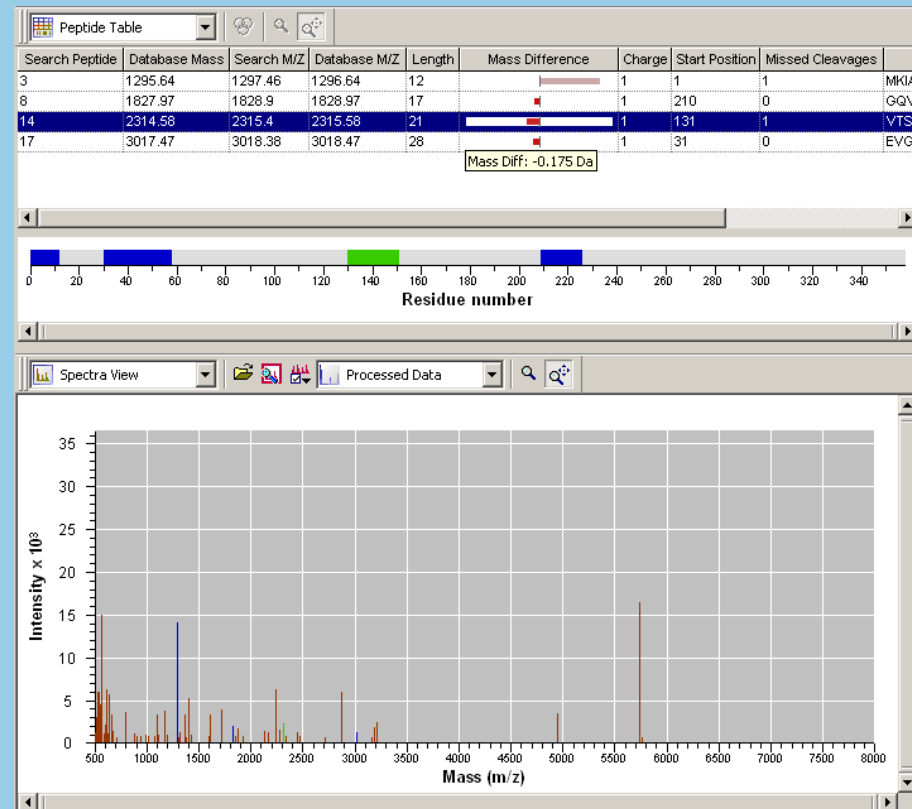
$$\lambda_q \sim \text{gamma}(a_q, b_q)$$

$$\Pr(P_y \mid k_i = k^*, a_{yij}) = \frac{\Gamma(a_q + q_{yij})}{\Gamma(a_q)} \frac{b_q^{q_{yij}}}{(b_q + r)^{a_q + q_{yij}}}.$$

Results display.



Results display.



“Does it work?”

- Bayesian inference.
- Is our belief structure *valid*?
 - “model”
 - “prior”
 - calibration

Diagnostic checking – prior predictive distribution.

- Are we using all of the available information?

The “glass slipper”

What if $k^* \notin S$?

Simple normal example (e.g. slipper sizes).

Collection of “items” with “true values” $X_i \sim N(\mu, \sigma_X^2)$.

Sample from item i . Observe Y_i where

$$Y_i | X_i \sim N(X_i, \sigma_Y^2).$$

Find a new, unknown, item, with unknown X , then

$$Y \sim N(\mu, \sigma_X^2 + \sigma_Y^2).$$

Assume, for now, that we know the values of μ , σ_X^2 , σ_Y^2 .

Database containing n known X values, x_1, \dots, x_n and we suppose that there are m other items not in the database. We observe a sample from an unidentified item and make the observation y .

Prior probabilities $p_1^{(0)}, \dots, p_n^{(0)}$ for items in the database and $p_{n+1}^{(0)}, \dots, p_{n+m}^{(0)}$ for items not in the database.

$$f(y, a, b) = \frac{1}{\sqrt{2\pi b}} \exp \left\{ -\frac{1}{2b}(y - a)^2 \right\}.$$

Then posterior probabilities, for $1 \leq i \leq n$,

$$p_i^{(1)} \propto k_i = p_i^{(0)} f(y, x_i, \sigma_Y^2).$$

and, for $n + 1 \leq i \leq n + m$,

$$p_i^{(1)} \propto k_i = p_i^{(0)} f(y, \mu, \sigma_X^2 + \sigma_Y^2).$$

Posterior probability that the sample came from an item not in the database, i.e. *any* item not in the database, is

$$P_O^1 = \frac{\sum_{j=n+1}^m k_j}{\sum_{j=1}^n k_j + \sum_{j=n+1}^m k_j}.$$

Suppose $p_1^{(0)} = \dots = p_n^{(0)} = p_0^{(0)}$ and $p_{n+1}^{(0)} = \dots = p_{n+m}^{(0)} = Qp_0^{(0)}$.

Now $np_0^{(0)} + mQp_0^{(0)} = 1$ so

$$Q = \frac{1 - np_0^{(0)}}{mp_0^{(0)}} = \frac{P_O^{(0)}}{mp_0^{(0)}}$$

where

$$P_O^{(0)} = \frac{Qm}{n + Qm} = 1 - np_0^{(0)} = 1 - P_I^{(0)}$$

The posterior probability that the sample came from an item not in the database becomes

$$P_O^{(1)} = \frac{P_O^{(0)} f(y, \mu, \sigma_X^2 + \sigma_Y^2)}{P_I^{(0)} \bar{f}(y, x_1, \dots, x_n, \sigma_Y^2) + P_O^{(0)} f(y, \mu, \sigma_X^2 + \sigma_Y^2)}$$

where

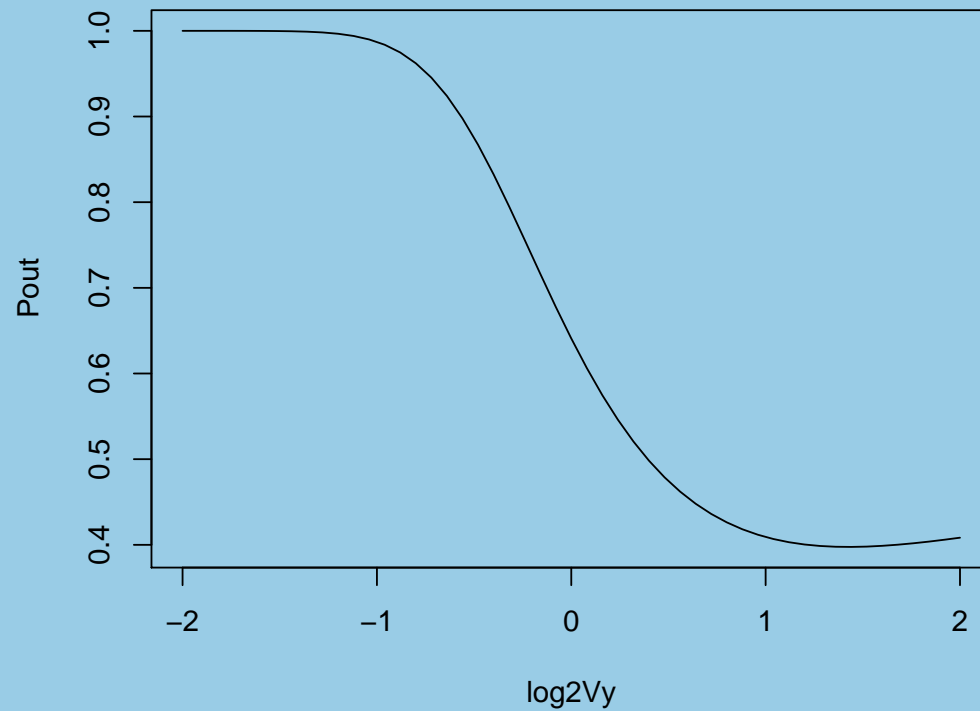
$$\bar{f}(y, x_1, \dots, x_n, \sigma_Y^2) = \frac{1}{n} \sum_{i=1}^n f(y, x_i, \sigma_Y^2).$$

Example: Database, size 10

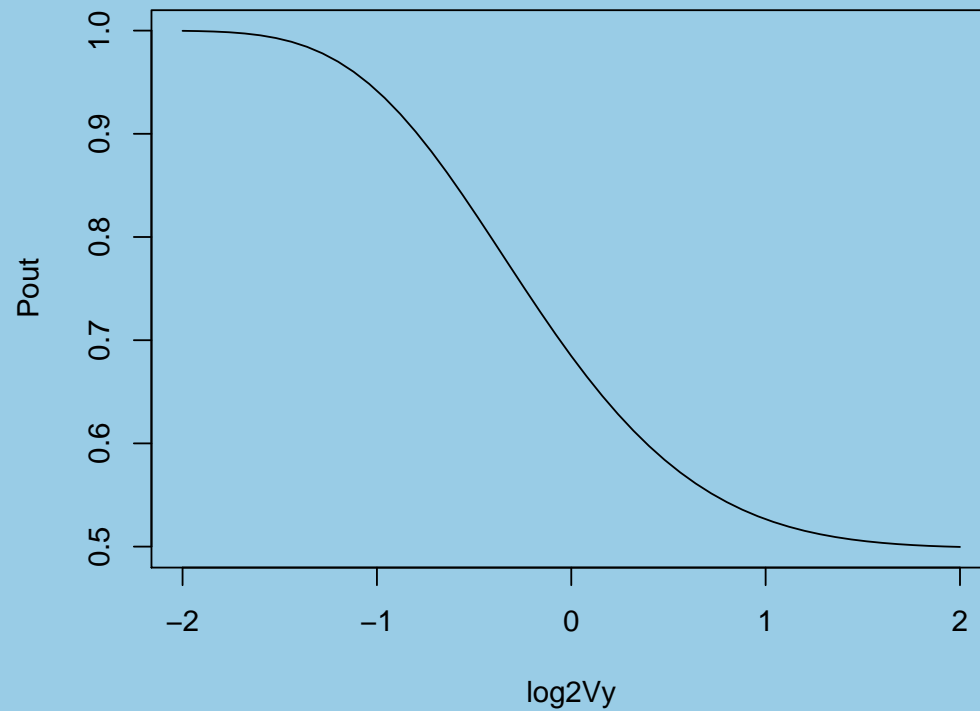
“Database” values:

-0.61	1.64	-0.38	-0.70	-0.13
0.28	1.43	1.27	1.38	0.55

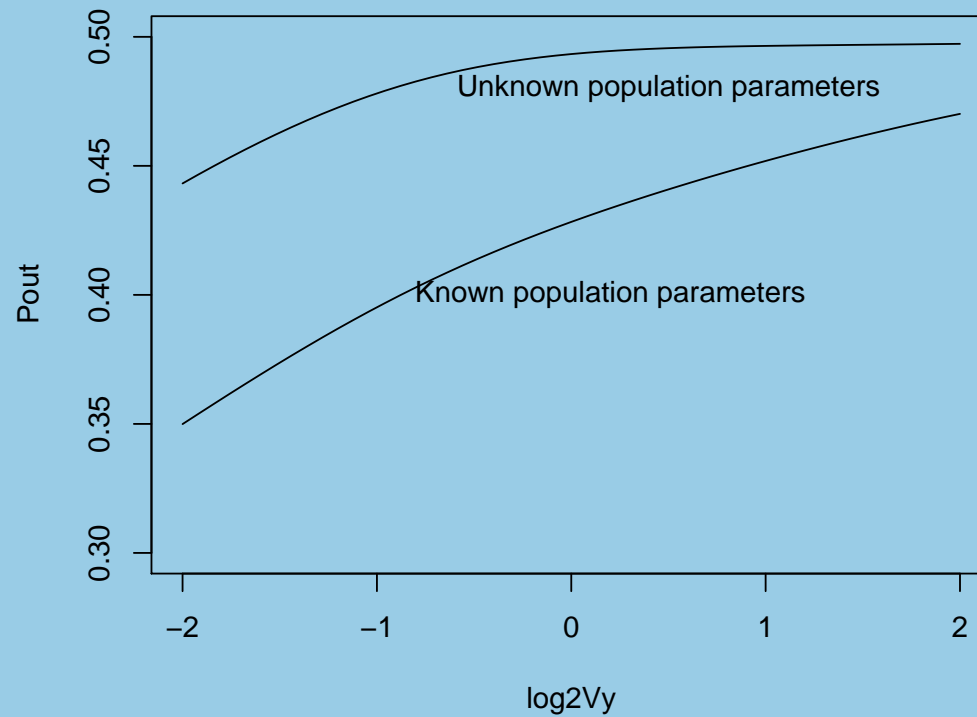
$$P_O^{(0)} = P_I^{(0)} = 0.5$$



Example: $P_O^{(1)}$ against $\log_2(\sigma_Y^2)$, $\sigma_X^2 = 1$, $\mu = 0$, $y = 5$.



$P_O^{(1)}$ against $\log_2(\sigma_Y^2)$, $\sigma_X^2 \sim \text{IG}(1, 0.1)$, $\mu \sim N(0, 10)$, $y = 5$.



Example: $P_O^{(1)}$ against $\log_2(\sigma_Y^2)$, $y = 1.3$.

Application to protein matching

- Mass range, width r .
- Within range, masses from “unknown” protein: Poisson process with rate λ_u .
- Each of these masses has, independently, a probability π of appearing as a peak.

Probability (density) that such an “unknown” protein would give rise to n_a observed peaks in particular locations is

$$e^{-\lambda_u \pi r} (\lambda_u \pi)^{n_a}.$$

Additional peaks in P_y must be “extras”. Use (5) and sum over possible allocations. Obtain a “likelihood” for an “unknown protein”

$$f_u(y, \lambda_u, \pi, \lambda_q, r) =$$

$$\sum_{n_a=0}^{n_y} \binom{n_y}{n_a} e^{-\lambda_u \pi r} (\lambda_u \pi)^{n_a} e^{\lambda_q \tau} \lambda_q^{n_y - n_a}$$

Allow for uncertainty in $\lambda_u\pi$ and in λ_q :

$$\lambda_u\pi \sim \text{gamma}(a_u, b_u)$$

$$\lambda_q \sim \text{gamma}(a_q, b_q)$$

$$L_{yo} = \sum_{n_a=0}^{n_y} \binom{n_y}{n_a} G_u(n_a) G_q(n_a)$$

where

$$G_u(n_a) = \frac{\Gamma(a_u + n_a)}{\Gamma(a_u)} \frac{b_u^{a_u}}{(b_u + r)^{a_u + n_a}}$$

$$G_q(n_a) = \frac{\Gamma(a_q + n_y - n_a)}{\Gamma(a_q)} \frac{b_q^{a_q}}{(b_q + r)^{a_q + n_y - n_a}}$$

Imagine prior probabilities $p_{n+1}^{(0)}, \dots, p_{n+m}^{(0)}$ for the m hypothetical “unknown” proteins and suppose that these are not associated with different beliefs about $\lambda_u \pi$.

Let

$$\mathbb{E} \left(\sum_{j=1}^m p_{n+j}^{(0)} \right) = P_0^{(0)}.$$

Then

$$\begin{aligned}\Pr(k^* = k_i|y) &= p_i^{(1)} \\ &= \frac{p_i^{(0)} L_{yi}}{\sum_{j=1}^n p_j^{(0)} L_{yj} + P_0^{(0)} L_{yo}}.\end{aligned}$$

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