MAS3902

Bayesian Inference

Solutions: Problems Class 1

Semester 1, 2019-20

10. (i) The likelihood function is

$$f(\boldsymbol{x}|\theta) = \prod_{i=1}^{n} \frac{\theta}{x_i^{\theta+1}} = \theta^n \exp\left\{-(\theta+1) \sum_{i=1}^{n} \log x_i\right\} \propto \theta^n \exp\left\{-n \log \bar{x}_g \theta\right\},\,$$

where $\bar{x}_g = \sqrt[n]{\prod_{i=1}^n x_i}$ is the geometric mean of the observations. Therefore the conjugate prior distribution is a Gamma Ga(g,h) distribution. Using Bayes Theorem, the posterior density is

$$\pi(\theta|\mathbf{x}) \propto \pi(\theta) f(\mathbf{x}|\theta)$$

$$\propto \frac{h^g \theta^{g-1} e^{-h\theta}}{\Gamma(g)} \times \theta^n e^{-n\log \bar{x}_g \theta}, \qquad \theta > 0,$$

that is, $\theta | \mathbf{x} \sim Ga(G = g + n, H = h + n \log \bar{x}_g)$.

We saw in Example 1.6 that to make a gamma distribution vague, we take $g \to 0$ and $h \to 0$. Therefore using a vague prior distribution gives the posterior distribution as $\theta | \mathbf{x} \sim Ga(n, n \log \bar{x}_a)$.

(ii) The asymptotic posterior distribution (as $n \to \infty$) is

$$\theta | \mathbf{x} \sim N\left(\hat{\theta}, J(\hat{\theta})^{-1}\right)$$
 ,

where

$$J(\theta) = -\frac{\partial^2}{\partial \theta^2} \log f(\mathbf{x}|\theta) = \frac{n}{\theta^2}.$$

Now

$$\frac{\partial}{\partial \theta} \log f(\mathbf{x}|\theta) = 0 \qquad \Longrightarrow \qquad \frac{n}{\hat{\theta}} - n \log \bar{x}_g = 0$$

$$\Longrightarrow \qquad \hat{\theta} = 1 / \log \bar{x}_g$$

$$\Longrightarrow \qquad J(\hat{\theta})^{-1} = \frac{1}{n(\log \bar{x}_g)^2}.$$

Therefore, for large n, the posterior distribution for θ is

$$\theta | \mathbf{x} \sim N\left(\frac{1}{\log \bar{x}_g}, \frac{1}{n(\log \bar{x}_g)^2}\right)$$
 approximately.

Note that the posterior distribution is centred on the likelihood mode and its variance tends to zero as $n \to \infty$.

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11. (i) We will consider the general case in which the prior distribution is a mixture distribution with component distributions

$$\pi_1(\mu) = N(b_1, 1/d_1)$$
 and $\pi_2(\mu) = N(b_2, 1/d_2)$

and (prior) weights p_1 and p_2 .

We have already seen that combining a random sample of size n from a normal $N(\mu, 1/\tau)$ distribution (with h known) with a normal N(b, 1/d) prior distribution results in a normal N(B, 1/D) posterior distribution where

$$B = \frac{db + n\tau \bar{x}}{d + n\tau}$$
 and $D = d + n\tau$.

Therefore, the (overall) posterior distribution will be a mixture distribution with component distributions

$$\pi_1(\mu|\mathbf{x}) = N(B_1, 1/D_1)$$
 and $\pi_2(\mu|\mathbf{x}) = N(B_2, 1/D_2)$

where

$$B_i = \frac{d_i b_i + n \tau \bar{x}}{d_i + n \tau}, \qquad D_i = d_i + n \tau.$$

We now calculate the (posterior) weights p_1^* and $p_2^* = 1 - p_1^*$, which will depend on both prior information and the data. We have

$$p_1^* = rac{p_1 f_1(\mathbf{x})}{p_1 f_1(\mathbf{x}) + p_2 f_2(\mathbf{x})}$$
 and $p_2^* = 1 - p_1^*$

where

$$f_i(\mathbf{x}) = \frac{\pi_i(\mu) f(\mathbf{x}|\mu)}{\pi_i(\mu|\mathbf{x})}.$$

The likelihood function is

$$f(\mathbf{x}|\mu) = \left(\frac{\tau}{2\pi}\right)^{n/2} \exp\left\{-\frac{n\tau}{2}\left[s^2 + (\bar{x} - \mu)^2\right]\right\}.$$

Therefore, for i = 1, 2

$$f_{i}(\mathbf{x}) = \frac{\pi_{i}(\mu) f(\mathbf{x}|\mu)}{\pi_{i}(\mu|\mathbf{x})}$$

$$= \frac{\left(\frac{d_{i}}{2\pi}\right)^{1/2} \exp\left\{-\frac{d_{i}}{2}(\mu - b_{i})^{2}\right\} \times \left(\frac{\tau}{2\pi}\right)^{n/2} \exp\left\{-\frac{n\tau}{2}\left[s^{2} + (\bar{x} - \mu)^{2}\right]\right\}}{\left(\frac{D_{i}}{2\pi}\right)^{1/2} \exp\left\{-\frac{D_{i}}{2}(\mu - B_{i})^{2}\right\}}$$

$$= \frac{c\sqrt{d_{i}}}{\sqrt{D_{i}}} \exp\left\{-\frac{1}{2}\left[d_{i}(\mu - b_{i})^{2} + n\tau(\bar{x} - \mu)^{2} - D_{i}(\mu - B_{i})^{2}\right]\right\}$$

$$= \cdots$$

$$= \frac{c\sqrt{d_{i}}}{\sqrt{D_{i}}} \exp\left\{\frac{1}{2}\left[D_{i}B_{i}^{2} - d_{i}b_{i}^{2}\right]\right\}.$$

Hence

$$(p_1^*)^{-1} - 1 = \frac{p_2 f_2(\mathbf{x})}{p_1 f_1(\mathbf{x})}$$

$$= \frac{p_2 \frac{c \sqrt{d_2}}{\sqrt{D_2}} \exp\left\{\frac{1}{2} \left[D_2 B_2^2 - d_2 b_2^2\right]\right\}}{p_1 \frac{c \sqrt{d_1}}{\sqrt{D_1}} \exp\left\{\frac{1}{2} \left[D_1 B_1^2 - d_1 b_1^2\right]\right\}}$$

$$= \frac{p_2 \sqrt{D_1 d_2}}{p_1 \sqrt{D_2 d_1}} \exp\left\{\frac{1}{2} \left[D_2 B_2^2 - d_2 b_2^2 - D_1 B_1^2 + d_1 b_1^2\right]\right\}.$$

In the numerical case mentioned, with n=10, $\bar{x}=2.5$, $\tau=1$, (prior) component parameters $b_1=3.3$, $d_1=1/0.37^2$, $b_2=1.1$, $d_2=1/0.47^2$ and (prior) weights $p_1=0.2$, $p_2=0.8$, we have

$$B_1 = \frac{d_1 b_1 + n\tau \bar{x}}{d_1 + n\tau} = 2.8377, \qquad D_1 = d_1 + n\tau = \frac{1}{0.2404^2},$$

$$B_2 = \frac{d_2 b_2 + n\tau \bar{x}}{d_2 + n\tau} = 2.0637, \qquad D_2 = d_2 + n\tau = \frac{1}{0.2624^2},$$

and $p_1^* = 0.6150$, $p_2^* = 0.3850$. Therefore, the posterior distribution is $\pi(\mu|\mathbf{x}) = 0.6150 \, N(2.8377, 0.2404^2) + 0.3850 \, N(2.0637, 0.2624^2).$

(ii) The prior mean is

$$E(\mu) = p_1 E_1(\mu) + p_2 E_2(\mu) = 0.2 \times 3.3 + 0.8 \times 1.1 = 1.54.$$

Also

$$E(\mu^2) = p_1 E_1(\mu^2) + p_2 E_2(\mu^2) = 0.2 \times (0.37^2 + 3.3^2) + 0.8 \times (0.47^2 + 1.1^2) = 3.3501$$

whence the variance of the prior distribution is

$$Var(\mu) = E(\mu^2) - E(\mu)^2 = 3.3501 - 1.54^2 = 0.9785 = 0.9892^2.$$

The posterior mean is

$$E(\mu|\mathbf{x}) = p_1^* E_1(\mu|\mathbf{x}) + p_2^* E_2(\mu|\mathbf{x}) = 0.6150 \times 2.8377 + 0.3850 \times 2.0637 = 2.5397.$$

Also

$$E(\mu^{2}|\mathbf{x}) = p_{1}^{*}E_{1}(\mu^{2}|\mathbf{x}) + p_{2}^{*}E_{2}(\mu^{2}|\mathbf{x})$$

= 0.6150 × (0.2404² + 2.8377²) + 0.3850 × (0.2624² + 2.0637²)
= 6.6540

whence the variance of the posterior distribution is

$$Var(\mu|\mathbf{x}) = E(\mu^2|\mathbf{x}) - E(\mu|\mathbf{x})^2 = 6.6540 - 2.5397^2 = 0.2039 = 0.4516^2.$$

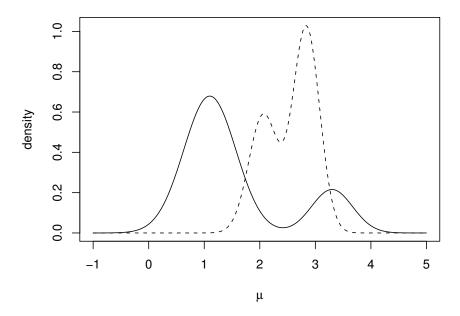


Figure 1: Prior (dashed) and posterior (solid) densities for μ

(iii) The prior and posterior distributions are bi-modal (see Figure 1). However, observing $\bar{x} = 2.5$ has transferred more weight to the component with the larger mean.

(iv) The prior probability that μ exceeds 2.5 is

$$Pr(\mu > 2.5) = \int_{2.5}^{\infty} \pi(\mu) d\mu$$

$$= \int_{2.5}^{\infty} \{ p_1 \pi_1(\mu) + p_2 \pi_2(\mu) \} d\mu$$

$$= p_1 \int_{2.5}^{\infty} \pi_1(\mu) d\mu + p_2 \int_{2.5}^{\infty} \pi_2(\mu) d\mu$$

$$= p_1 Pr_1(\mu > 2.5) + p_2 Pr_2(\mu > 2.5)$$

$$= 0.1981$$

using the command 0.2*(1-pnorm(2.5,3.3,0.37))+0.8*(1-pnorm(2.5,1.1,0.47)) Similarly, the posterior probability that μ exceeds 2.5 is

$$Pr(\mu > 2.5|\mathbf{x}) = \int_{2.5}^{\infty} \pi(\mu|\mathbf{x}) d\mu$$

= $p_1^* Pr_1(\mu > 2.5|\mathbf{x}) + p_2^* Pr_2(\mu > 2.5|\mathbf{x})$
= 0.5843

using the command

0.6150*(1-pnorm(2.5,2.8377,0.2404))+0.3850*(1-pnorm(2.5,2.0637,0.2624))

Note that incorporating the data has substantially increased the probability of μ exceeding 2.5.

13. From the results in section 2.2, we have

$$E(\mu|\mathbf{x}) - E(\mu) > 0 \iff \frac{bc + n\bar{\mathbf{x}}}{c + n} - b > 0 \iff bc + n\bar{\mathbf{x}} - b(c + n) > 0 \iff \bar{\mathbf{x}} - b > 0.$$

Therefore

$$E(\mu|\mathbf{x}) > E(\mu) \iff \bar{\mathbf{x}} > E(\mu).$$

Notice that we can write the posterior mean as a convex combination of the prior and sample means:

$$B = \alpha b + (1 - \alpha)\bar{x}$$
 where $\alpha = \frac{c}{c + n} \in (0, 1)$.