

Parameter-dependent Optimal Designs

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May 2010

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- Bayesian ideas are useful but need not entail a Bayesian analysis
- This talk illustrates some aspects of this using Michaelis-Menten experiments

Main example - Michaelis Menten studies

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where

- s is the substrate concentration, v the rate of reaction
- K is the *Michaelis* parameter; V_{\max} the maximum rate of reaction
- interest focusses on K and other quantities, such as V_{\max}/K

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- Substantial history to fitting this model exists.

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- Suppose we wish to estimate K as precisely as possible.

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- at s_j make $N\eta_j$ observations: $\eta_j > 0$, $\sum \eta_j = 1$

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Locally optimal design

Locally D-optimal design: $m = 2$, write $y_j = s_j / (K + s_j)$.

$$\Delta = \eta_1 \eta_2 y_1^2 y_2^2 (y_1 - y_2)^2$$

Optimal design $\eta_j = \frac{1}{2}$, $y_1 = \frac{1}{2}$, $y_2 = 1$ i.e. $s_1 = K$, $s_2 = \infty$

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So expectation involving ξ depends only on the K -marginal of π .

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- T some arbitrary 'large' scaled concentration - herein $T = 10$

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		$\log \kappa \sim \text{Unif}$	$\kappa_L = 10^{-5}$			
t	4.4e-5	4.9e-4	3.8e-3	0.029	0.29	10
η	0.12	0.10	0.11	0.14	0.23	0.30

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- So what happens if $\pi(V_{\max})$ is very concentrated?

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 - This work was later formalised by Bernardo (1979)

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- So choose ξ to maximise $\mathbb{E}_{\mathbf{x}|\xi}(\mathcal{I}_1 - \mathcal{I}_0)$, which amounts to

$$\int \log \pi(\theta|\mathbf{x}, \xi)\pi(\theta, \mathbf{x}|\xi)d\theta d\mathbf{x} = \int \log \pi(\theta|\mathbf{x}, \xi)\pi(\mathbf{x}|\theta, \xi)\pi(\theta)d\theta d\mathbf{x}$$

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- Commonly used approximation is $\pi(\theta|\mathbf{x}, \xi) = N(\hat{\theta}, \mathcal{I}(\hat{\theta})^{-1})$
- From this we obtain $\mathbb{E}_{\mathbf{x}|\xi}(\mathcal{J}_1 - \mathcal{J}_0) \approx \frac{1}{2}\mathbb{E}_{\theta}(\log \det \mathcal{I}(\theta))$

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- The criterion is now:

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$$\mathbb{E}_{\theta}[\log \det(\mathcal{I}(\theta) + R)] = \mathbb{E}_{\theta}[\log \det(N\sigma^{-2}\mathcal{M} + R)]$$

- Now N and σ^2 do not 'scale out' of the problem

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$$\mathcal{M} = \begin{pmatrix} A_0 & & \\ -V_{\max} A_1 & & \\ & V_{\max}^2 A_2 & \end{pmatrix}$$

- Also we have

$$R = \begin{pmatrix} \text{var}_{\pi}(V_{\max})^{-1} & & \\ 0 & & \\ & \text{var}_{\pi}(K)^{-1} & \end{pmatrix} = \begin{pmatrix} R_V & & \\ 0 & & \\ & K_U^{-2} R_{\kappa} & \end{pmatrix}$$

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$$\log \left[\left(\frac{R_V \sigma^2}{N} + A_0 \right) \left(\frac{R_\kappa \sigma^2}{NV_{\max}^2} + A_2 \right) - A_1^2 \right]$$

whereas before it was simply

$$\log [A_0 A_2 - A_1^2]$$

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- Write $\tilde{V} = V_{\max}/\sigma_V$
- Need to maximise

$$\mathbb{E}_{\kappa, \tilde{V}} \log \left[\left(\frac{1}{N\lambda} + A_0 \right) \left(\frac{1}{N\lambda \tilde{V}^2 \text{var}(\kappa)} + A_2 \right) - A_1^2 \right]$$

with prior for κ as before and for $\tilde{V} \sim N(V_0, 1)$

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0.1	0.04	0.48		
	5.0	0.52		

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- The issue of a prior for design and a prior for analysis is discussed in Cox and Reid *The Theory of the Design of Experiments*

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