

## Gradient, Divergence and Curl

### Question 1

[5 marks]

Find the directional derivative of the scalar field  $f(x, y, z) = xyz$  in the direction of  $\mathbf{b} = (0, 4, 3)$ , at the point  $\mathbf{r} = (-2, 3, 4)$ .

### Solution

The directional derivative is given by  $\partial f / \partial b = \hat{\mathbf{b}} \cdot \nabla f$ .

Here  $\mathbf{b} = (0, 4, 3)$ , so  $|\mathbf{b}| = \sqrt{0 + 16 + 9} = 5$ , and  $\hat{\mathbf{b}} = \mathbf{b}/|\mathbf{b}| = (0, 4/5, 3/5)$ .

$f(x, y, z) = xyz$ , so  $\nabla f = (\partial f / \partial x, \partial f / \partial y, \partial f / \partial z) = (yz, xz, xy)$ ; at point  $\mathbf{r} = (-2, 3, 4)$ ,  $\nabla f = (12, -8, -6)$ .

So

$$\frac{\partial f}{\partial b} = \hat{\mathbf{b}} \cdot \nabla f = \left(0, \frac{4}{5}, \frac{3}{5}\right) \cdot (12, -8, -6) = 0 + \frac{-32}{5} + \frac{-18}{5} = -10.$$

### Question 2

[6+4 marks]

(a) Expand and simplify  $\nabla \cdot (f(r)\mathbf{r})$ , where  $r = |\mathbf{r}|$ ,  $\mathbf{r} = (x, y, z)$  and  $f$  is a differentiable scalar field.

(b) (\*) Find  $f(r)$  such that  $\nabla \cdot (f(r)\mathbf{r}) = 0$ .

### Solution

(a) Since  $\mathbf{r} = (x, y, z)$ , we have  $f(r)\mathbf{r} = (f(r)x, f(r)y, f(r)z) = (xf(r), yf(r), zf(r))$ , so

$$\begin{aligned} \nabla \cdot (f(r)\mathbf{r}) &= \frac{\partial}{\partial x}(xf(r)) + \frac{\partial}{\partial y}(yf(r)) + \frac{\partial}{\partial z}(zf(r)) \\ &= f(r) + x \frac{df}{dr} \frac{x}{r} + f(r) + y \frac{df}{dr} \frac{y}{r} + f(r) + z \frac{df}{dr} \frac{z}{r} \\ &= 3f(r) + \frac{df}{dr} \frac{x^2 + y^2 + z^2}{r} = 3f(r) + r \frac{df}{dr}. \end{aligned}$$

Here we have used the product rule and chain rule to expand terms such as

$$\frac{\partial}{\partial x}(xf(r)) = f(r) \frac{\partial}{\partial x}(x) + x \frac{\partial}{\partial x}(f(r)) = f(r) + x \frac{\partial}{\partial x}(f(r)) = f(r) + x \frac{df}{dr} \frac{\partial r}{\partial x},$$

and have also used the result that  $\frac{\partial r}{\partial x} = \frac{x}{r}$ , just as we did in Question 4 of Exercises, Part 3. (Please see those solutions to recall where this result came from, and also for a fuller explanation of the use of the chain rule.)

Alternatively, using the subscript notation,

$$\begin{aligned} \nabla \cdot (f(r)\mathbf{r}) &= \frac{\partial}{\partial x_i}(f(r)x_i) = x_i \frac{\partial f(r)}{\partial x_i} + f(r) \frac{\partial x_i}{\partial x_i} = x_i f'(r) \frac{\partial r}{\partial x_i} + 3f(r) \\ &= f'(r)x_i \frac{x_i}{r} + 3f(r) = r f'(r) + 3f(r), \end{aligned}$$

where  $f'(r) = \frac{df}{dr}$ . (Remember about summation convention to get the factor 3 right.)

(b)  $\nabla \cdot (f(r)\mathbf{r}) = 0$  if  $3f(r) + rf'(r) = 0$ , where  $f'(r) = \frac{df}{dr}$ . This differential equation can be easily solved by separation of variables:

$$3f + r \frac{df}{dr} = 0 \Rightarrow \int \frac{df}{f} = -3 \int \frac{dr}{r} \Rightarrow \ln |f| = -3 \ln r + C \quad (\text{note that } r \geq 0) \Rightarrow f = Cr^{-3},$$

where  $C$  is an arbitrary constant.

### Question 3

[5 marks]

Expand and simplify  $\nabla \times (r\mathbf{r})$ , where  $r = |\mathbf{r}|$  and  $\mathbf{r} = (x, y, z)$ .

#### Solution

$$\nabla \times (r\mathbf{r}) = \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ rx & ry & rz \end{vmatrix}, \text{ so the } x\text{-component is given by } \left( \frac{\partial}{\partial y} rz - \frac{\partial}{\partial z} ry \right) = \left( \frac{yz}{r} - \frac{yz}{r} \right) =$$

0. From the symmetry with respect to cyclic permutations, we conclude that all the remaining components vanish too.

$$\begin{aligned} \text{Otherwise, using the subscript notation, } \nabla \times (r\mathbf{r}) &= \varepsilon_{ijk} \frac{\partial x_k r}{\partial x_j} = \varepsilon_{ijk} \left( \delta_{jk} r + x_k \frac{x_j}{r} \right) \\ &= \left( \varepsilon_{ijj} r + \frac{1}{r} \varepsilon_{ijk} x_j x_k \right) = \mathbf{0} + \frac{1}{r} \mathbf{r} \times \mathbf{r} = \mathbf{0}, \text{ since } \varepsilon_{ijj} = \mathbf{0} \text{ and } \mathbf{u} \times \mathbf{u} = \mathbf{0} \text{ for any vector } \mathbf{u}. \end{aligned}$$

Alternatively, using the identity of Question 4

$$\nabla \times (r\mathbf{r}) = \nabla r \times \mathbf{r} + r \nabla \times \mathbf{r} = \frac{1}{r} \mathbf{r} \times \mathbf{r} + \mathbf{0} = \mathbf{0}.$$

Note that the vector  $r\mathbf{f}(r)$  is **irrotational** for any  $f(r)$ , i.e., its curl vanishes.

### Question 4

[7 marks]

Show that  $\nabla \times (f\mathbf{v}) = \nabla f \times \mathbf{v} + f \nabla \times \mathbf{v}$ , where  $f(x, y, z)$  is a differentiable scalar field and  $\mathbf{v}(x, y, z)$  is a differentiable vector field.

#### Solution

We can take advantage of the symmetry with respect to cyclic permutations and only consider the  $x$ -component of the identity. Since

$$\nabla \times (f\mathbf{v}) = \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ fv_x & fv_y & fv_z \end{vmatrix} = \hat{\mathbf{x}} \left( \frac{\partial}{\partial y} fv_z - \frac{\partial}{\partial z} fv_y \right) + \hat{\mathbf{y}} \left( \frac{\partial}{\partial z} fv_x - \frac{\partial}{\partial x} fv_z \right) + \hat{\mathbf{z}} \left( \frac{\partial}{\partial x} fv_y - \frac{\partial}{\partial y} fv_x \right),$$

the  $x$ -component reduces to

$$v_z \frac{\partial f}{\partial y} + f \frac{\partial v_z}{\partial y} - v_y \frac{\partial f}{\partial z} - f \frac{\partial v_y}{\partial z} = \left( v_z \frac{\partial f}{\partial y} - v_y \frac{\partial f}{\partial z} \right) + f \left( \frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z} \right). \quad (1)$$

This cannot be simplified any further. In order to verify that the last expression is indeed equal to  $f \times \mathbf{v} + f \nabla \times \mathbf{v}$  (if it is not yet clear), it is useful to write out the  $x$ -component of the right-hand side of the identity to be proved:

$$\begin{aligned} [\nabla f \times \mathbf{v} + f \nabla \times \mathbf{v}]_x &= \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} & \frac{\partial f}{\partial z} \\ v_x & v_y & v_z \end{vmatrix}_x + f \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_x & v_y & v_z \end{vmatrix}_x \\ &= \left( v_z \frac{\partial f}{\partial y} - v_y \frac{\partial f}{\partial z} \right) + f \left( \frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z} \right), \end{aligned}$$

which is identical to Eq. (1).

Alternatively, using the subscript notation allows a very compact proof:

$$\nabla \times (f\mathbf{v}) = \varepsilon_{ijk} \frac{\partial}{\partial x_j} (fv_k) = \varepsilon_{ijk} \frac{\partial f}{\partial x_j} v_k + \varepsilon_{ijk} f \frac{\partial v_k}{\partial x_j} = \nabla f \times \mathbf{v} + f \nabla \times \mathbf{v}.$$

### Question 5

[3+3+5 marks]

Given that  $\mathbf{c} = (c_x, c_y, c_z)$  is a constant vector, and  $\mathbf{r} = (x, y, z)$  is the position vector, simplify the following expressions, expressing your answer in terms of  $\mathbf{c}$  wherever possible:

(a)  $\nabla(\mathbf{c} \cdot \mathbf{r})$ ;      (b)  $\mathbf{c}(\nabla \cdot \mathbf{r})$ ;      (c) (\*)  $\nabla \times (\mathbf{c} \times \mathbf{r})$ .

### Solution

(a) Here  $\mathbf{c} \cdot \mathbf{r}$  is a scalar (the dot product,  $\mathbf{c} \cdot \mathbf{r} = c_x x + c_y y + c_z z$ ), and the expression required is the gradient of this quantity:

$$\begin{aligned} \nabla(\mathbf{c} \cdot \mathbf{r}) &= \nabla(c_x x + c_y y + c_z z) \\ &= \left( \frac{\partial}{\partial x}(c_x x + c_y y + c_z z), \frac{\partial}{\partial y}(c_x x + c_y y + c_z z), \frac{\partial}{\partial z}(c_x x + c_y y + c_z z) \right) \\ &= (c_x, c_y, c_z) = \mathbf{c}. \end{aligned}$$

(Note that, since  $\mathbf{c}$  is a *constant* vector, all derivatives of any of its components vanish.)

(b) Here  $\nabla \cdot \mathbf{r}$  is a scalar quantity (the divergence of the position vector  $\mathbf{r}$ ), and the expression required is just this quantity times the vector  $\mathbf{c}$ :

$$\mathbf{c}(\nabla \cdot \mathbf{r}) = \mathbf{c} \left( \frac{\partial x}{\partial x} + \frac{\partial y}{\partial y} + \frac{\partial z}{\partial z} \right) = \mathbf{c}(1 + 1 + 1) = 3\mathbf{c}.$$

(c) Here  $\mathbf{c} \times \mathbf{r}$  is a vector quantity (the cross product of the two vectors involved), and the expression required is the curl of this vector product:

$$\mathbf{c} \times \mathbf{r} = \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ c_x & c_y & c_z \\ x & y & z \end{vmatrix} = (c_y z - c_z y, c_z x - c_x z, c_x y - c_y x).$$

So

$$\nabla \times (\mathbf{c} \times \mathbf{r}) = \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ (c_y z - c_z y) & (c_z x - c_x z) & (c_x y - c_y x) \end{vmatrix} = (c_x + c_x, c_y + c_y, c_z + c_z) = 2\mathbf{c}.$$

GRS

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